

Analyse nutzergenerierter Trajektorien von Fahrradfahrern

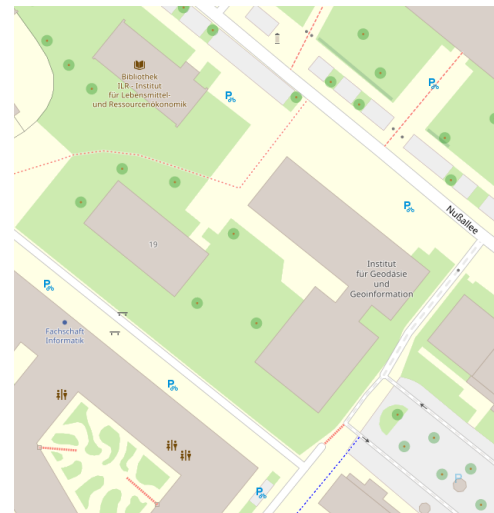
GeoIT Round Table NRW
29th March 2023

Jan-Henrik Haunert

Volunteered Geographic Information



OpenStreetMap.org



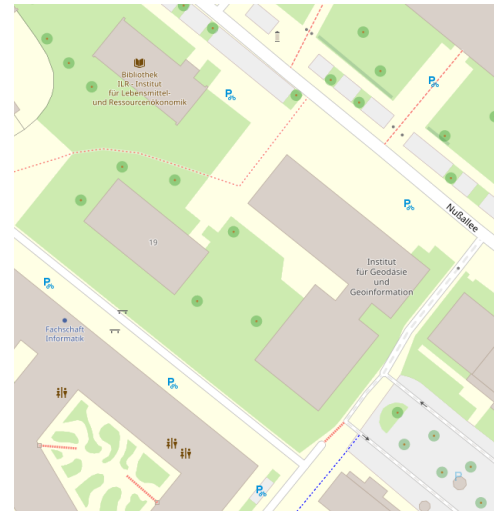
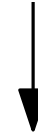
Volunteered Geographic Information



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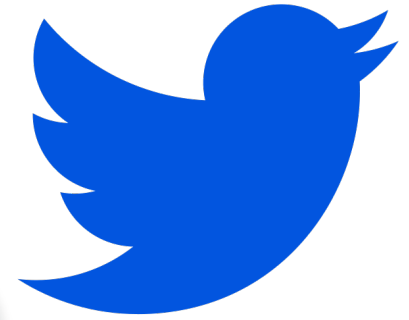
OpenStreetMap.org



Volunteered Geographic Information



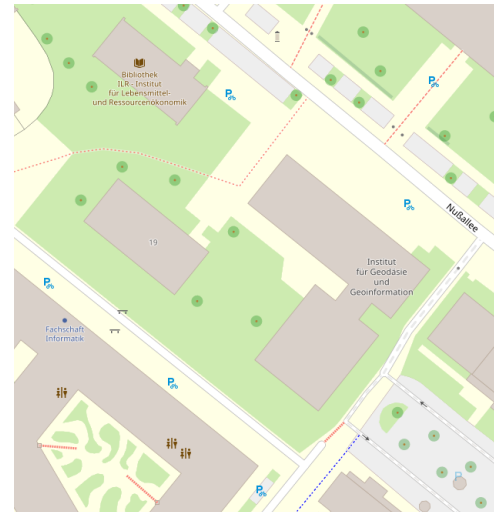
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Volunteered Geographic Information

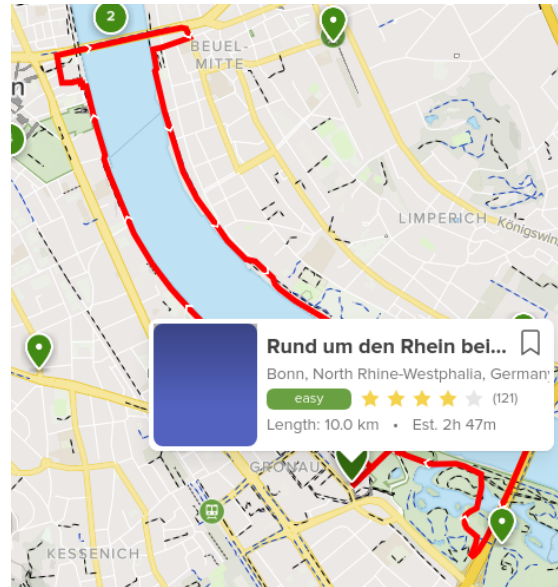


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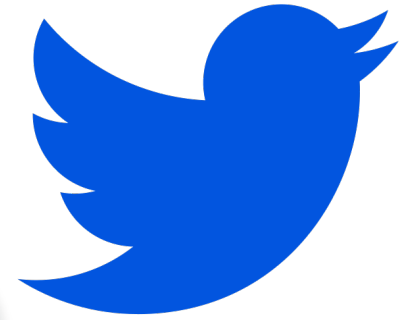
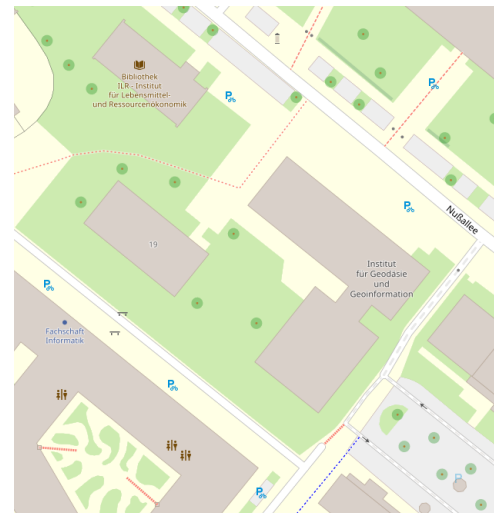


AllTrails.com

GPSies.com



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Volunteered Geographic Information



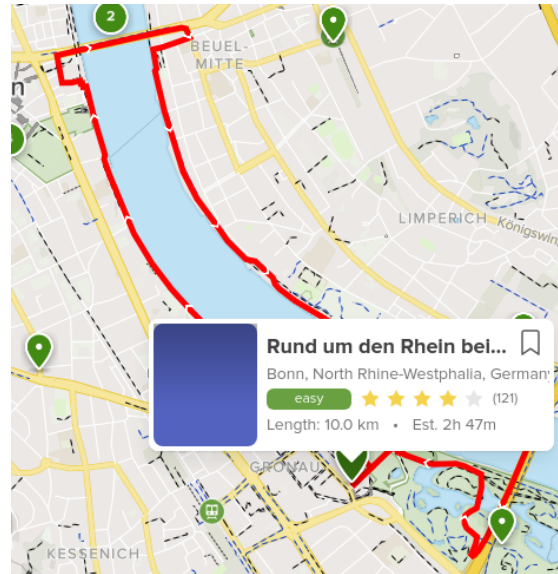
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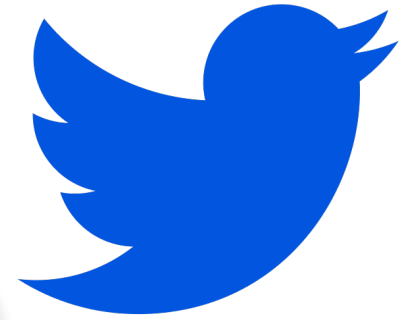
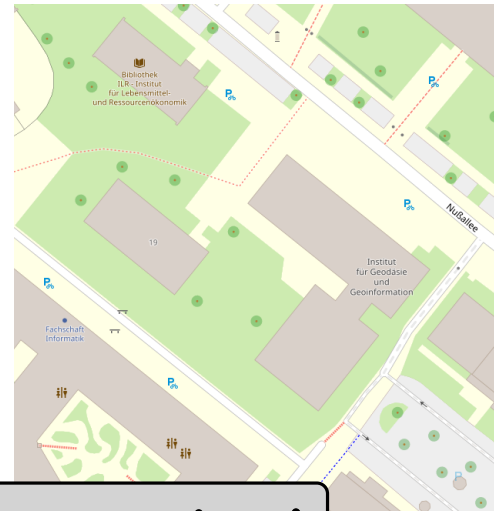



GPSies.com

AllTrails.com



OpenStreetMap.org

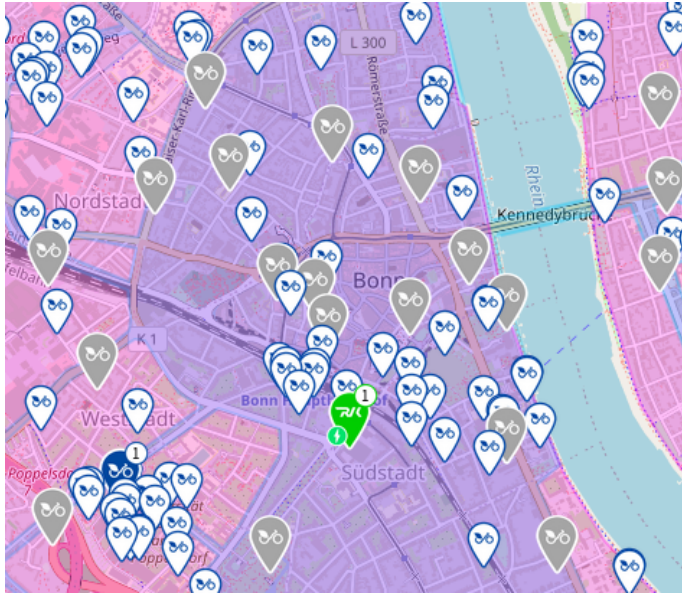


Twitter.com



high data heterogeneity!

VGI Trajectory Data

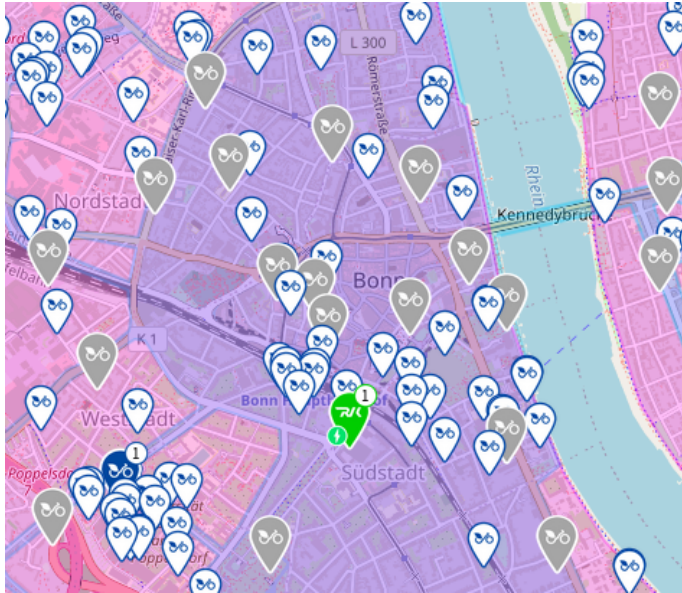


[1] www.nextbike.de/de/bonn



[2] www.bonn.de/radverkehr

VGI Trajectory Data



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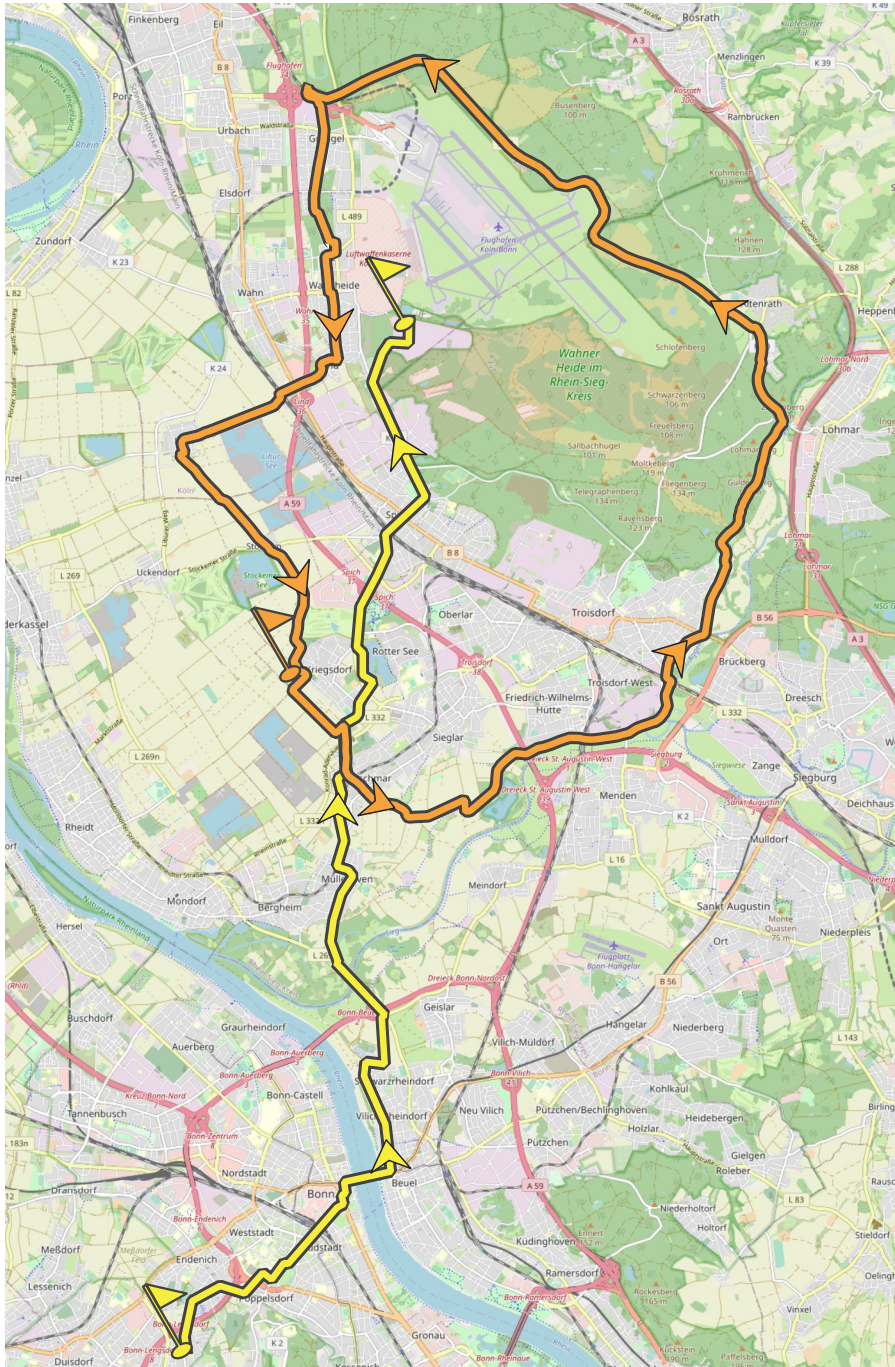


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+ data resembles user's view
"from user for user"

VGI Trajectory Data



- + data resembles user's view
"from user for user"
- **data heterogeneity**
 - user intention unknown
 - data quality hard to assess
- privacy concerns

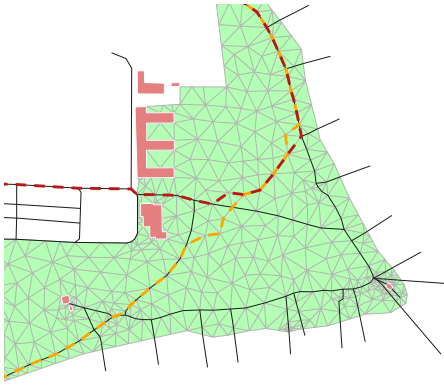
My Work

Preprocessing	Analysis	Visualization

My Work

Preprocessing

Map Matching

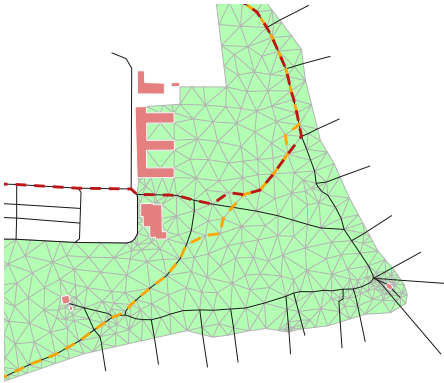


Analysis

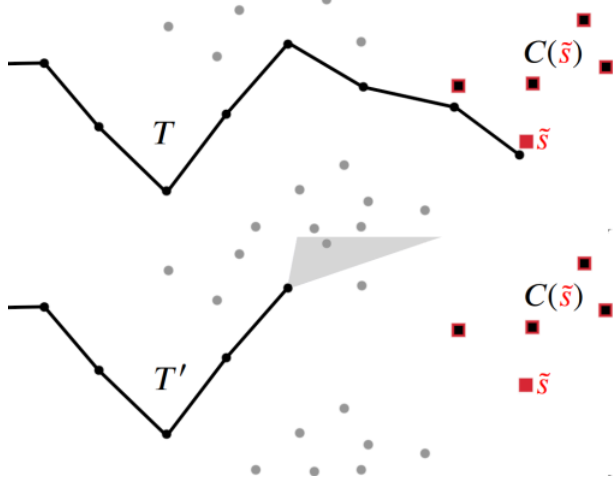
Visualization

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Map Matching



Privacy

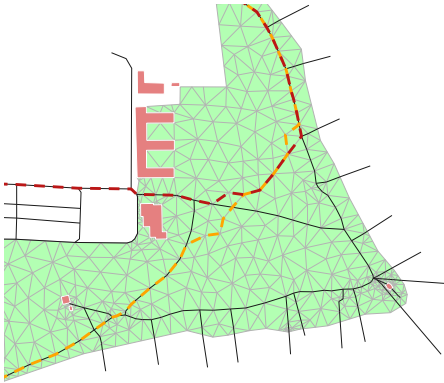


Analysis

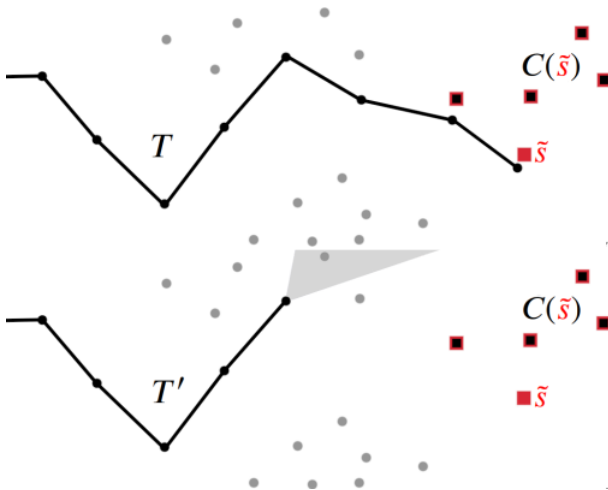
Visualization

Preprocessing

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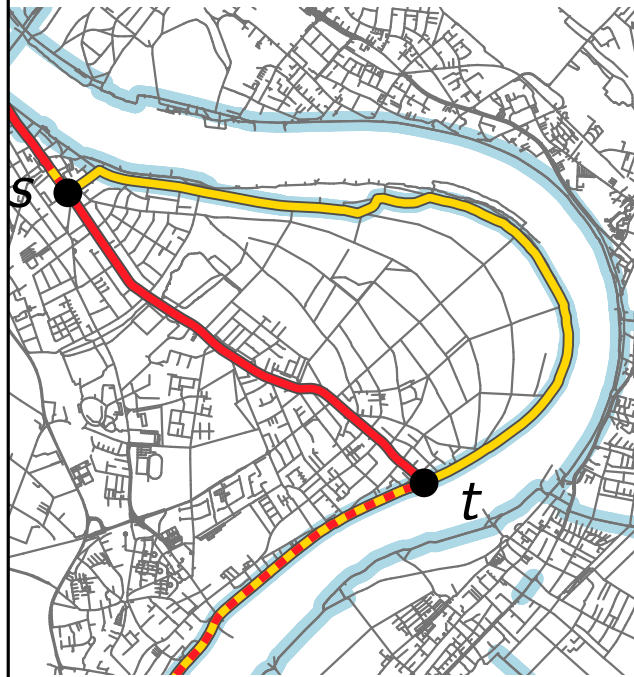


Privacy



Analysis

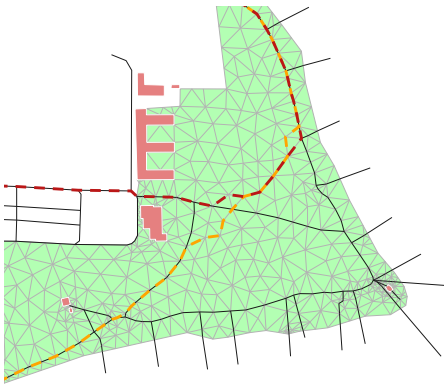
Inferring Routing Preferences



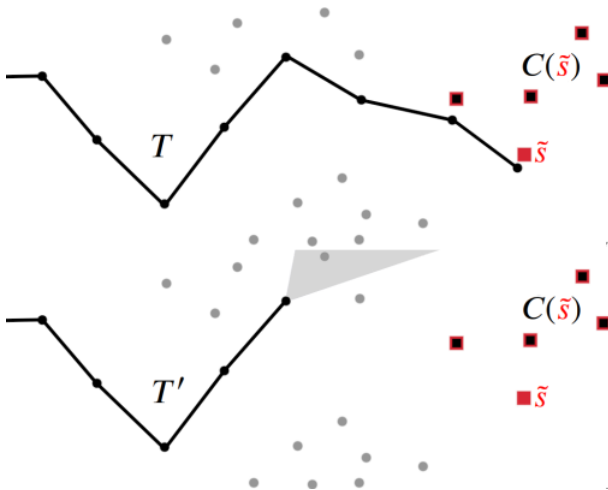
Visualization

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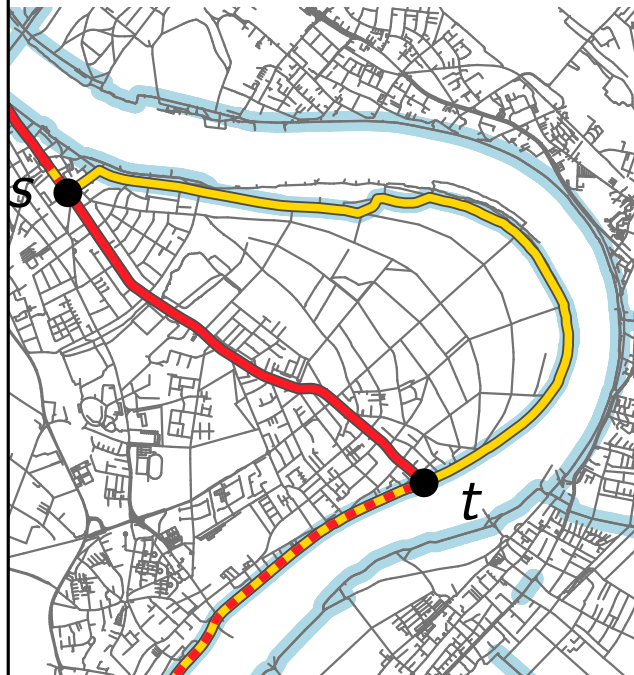


Privacy



Analysis

Inferring Routing Preferences



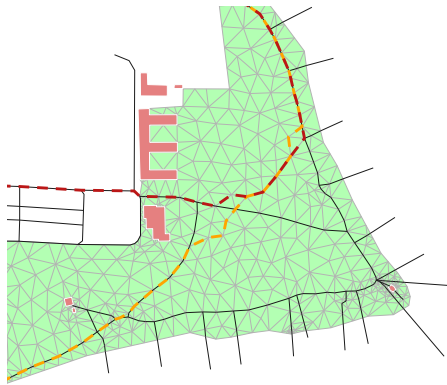
Visualization

Off-screen Evolution

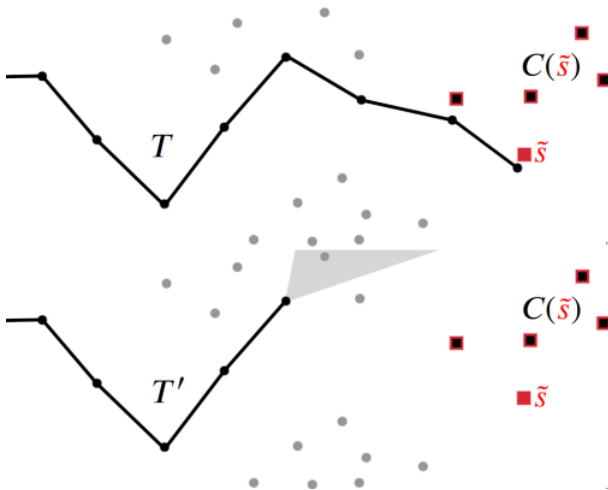


Preprocessing

Map Matching

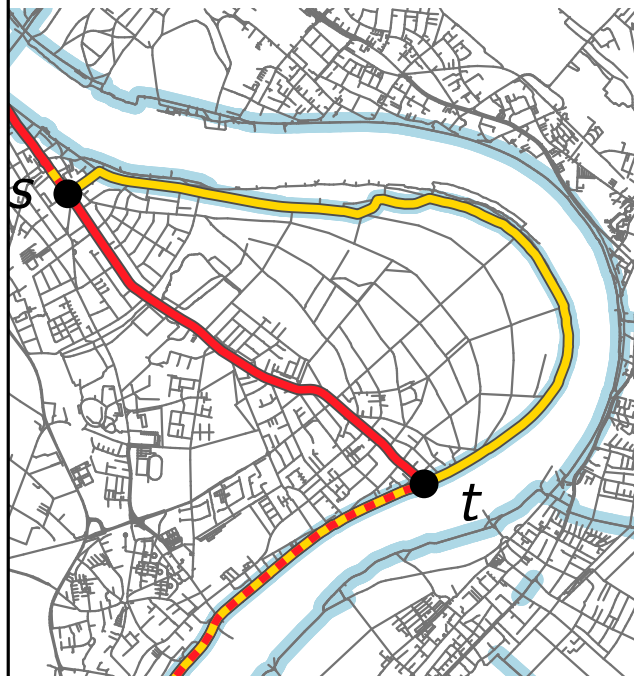


Privacy



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Inferring Routing Preferences



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Off-screen Evolution



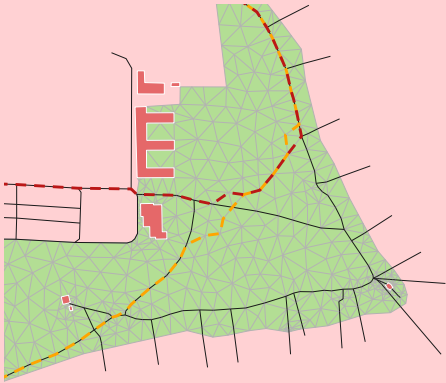
Travel-Time Maps



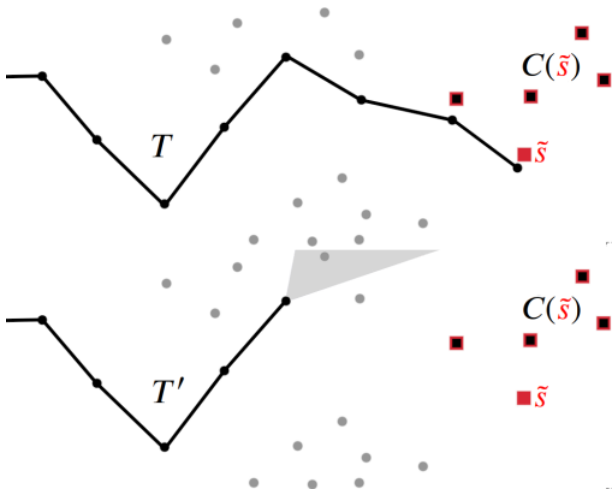
My Work

Preprocessing

Map Matching

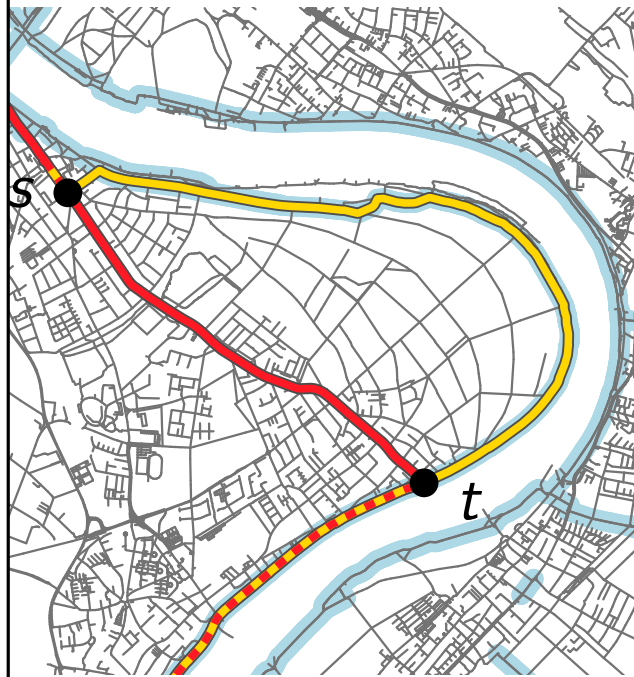


Privacy



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Map Matching



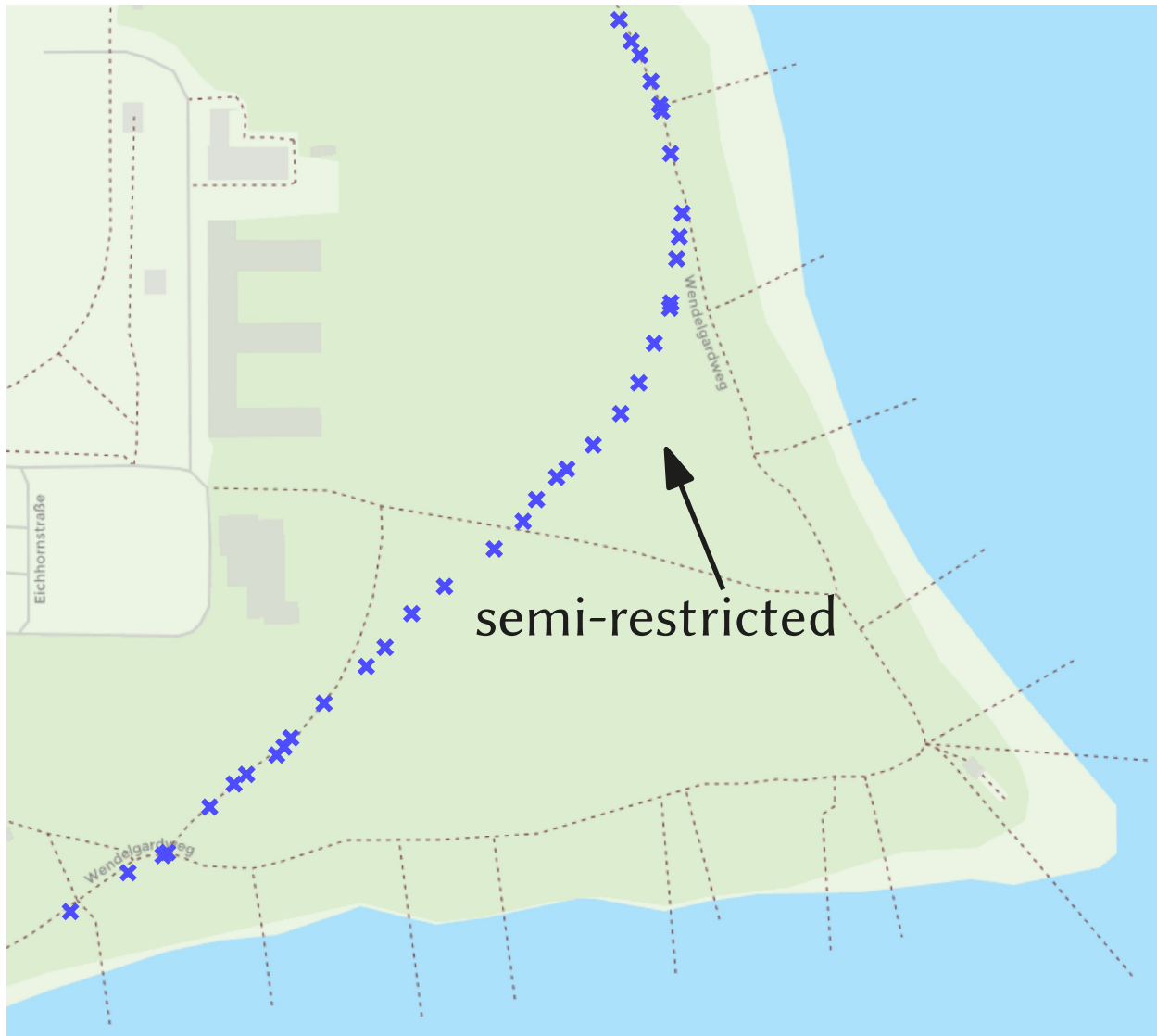
Map Matching



Use-cases for matched trajectories:

- comparison of trajectories
- lower storage space
 - fewer points
 - efficient index structures (Funke et al., 2019)
- inferring routing preferences
- ...

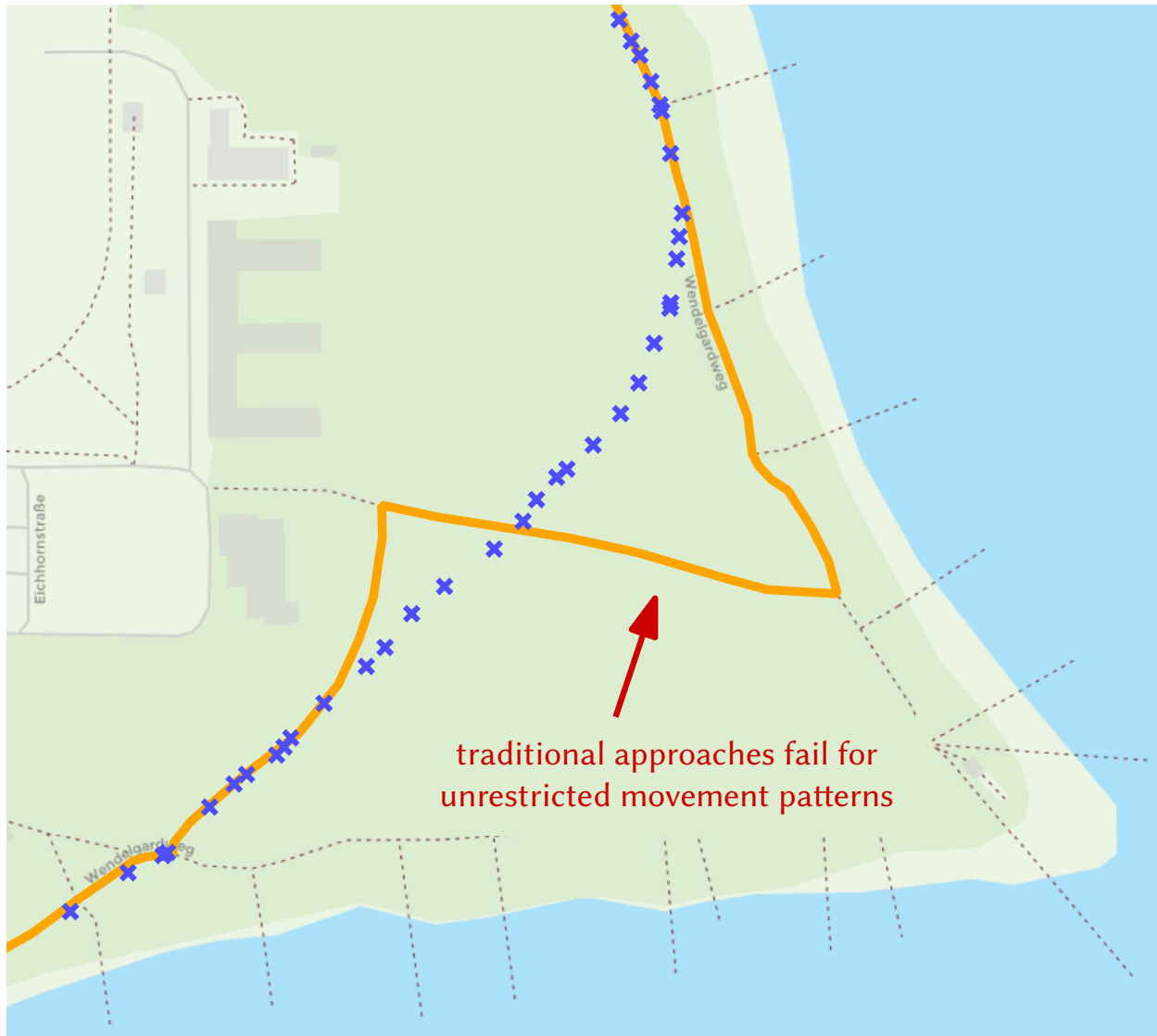
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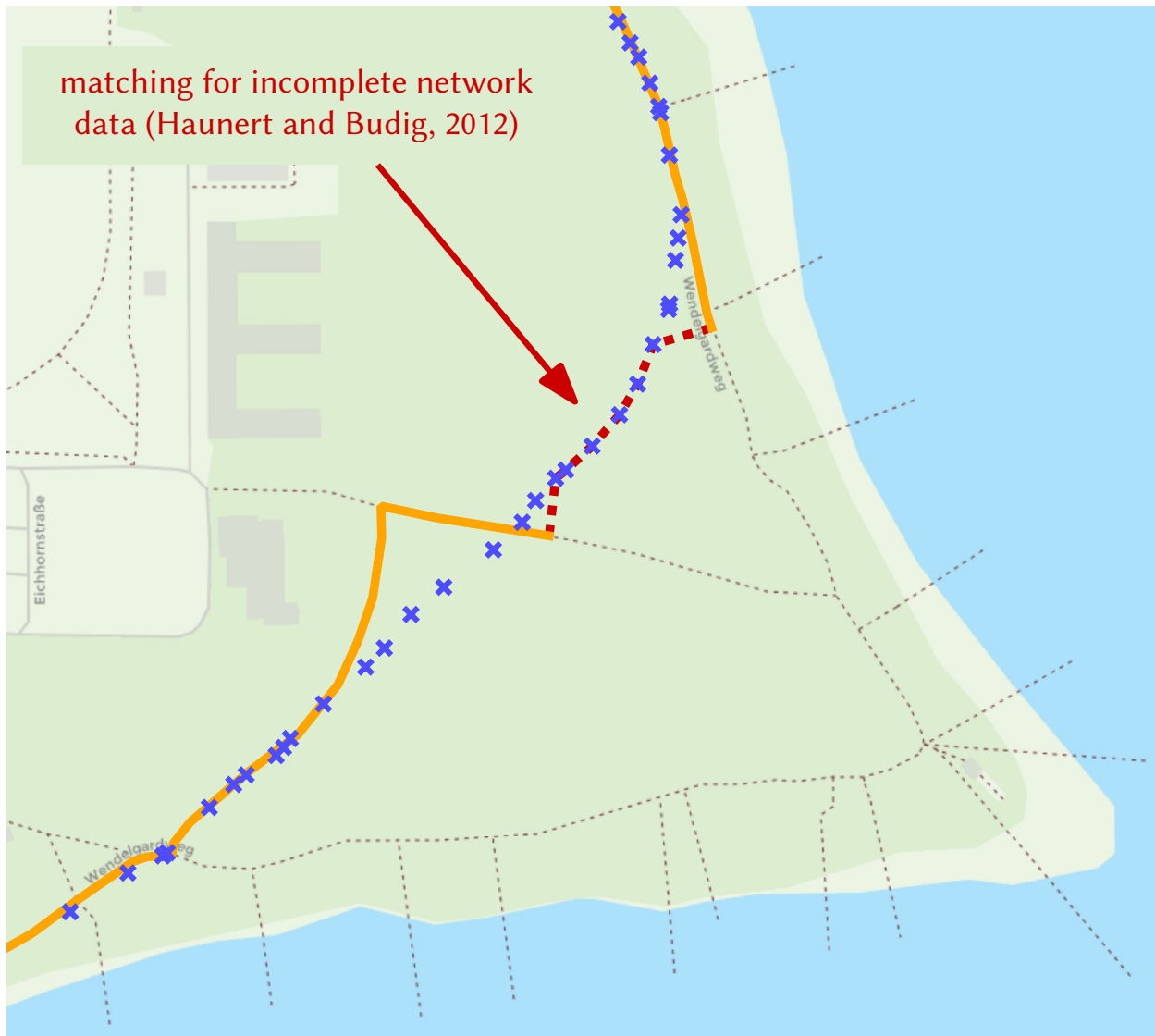
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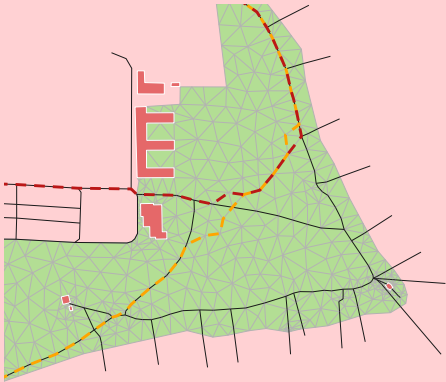


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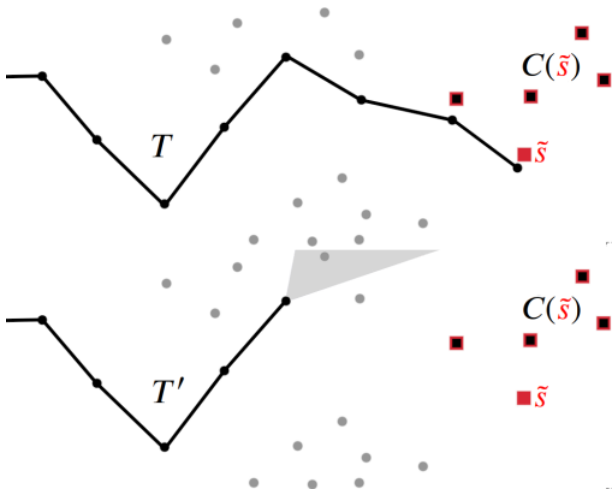
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Preprocessing

Map Matching

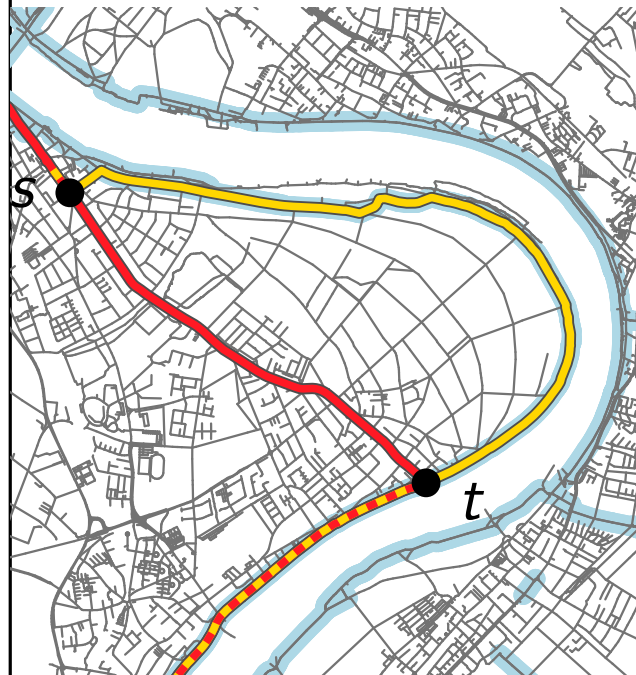


Privacy



Analysis

Inferring Routing Preferences



Visualization

Off-screen Evolution

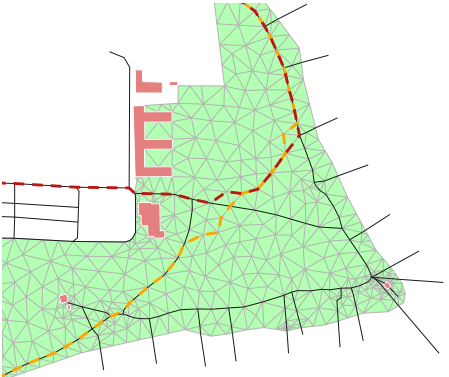


Travel-Time Maps



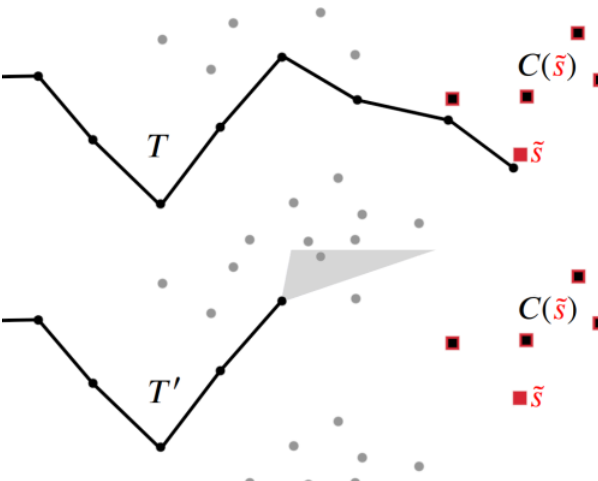
Preprocessing

Map Matching



A diagram illustrating map matching. It shows a green triangular mesh representing a road network. A red dashed line indicates a user's trajectory, and a yellow solid line shows the matched path on the map.

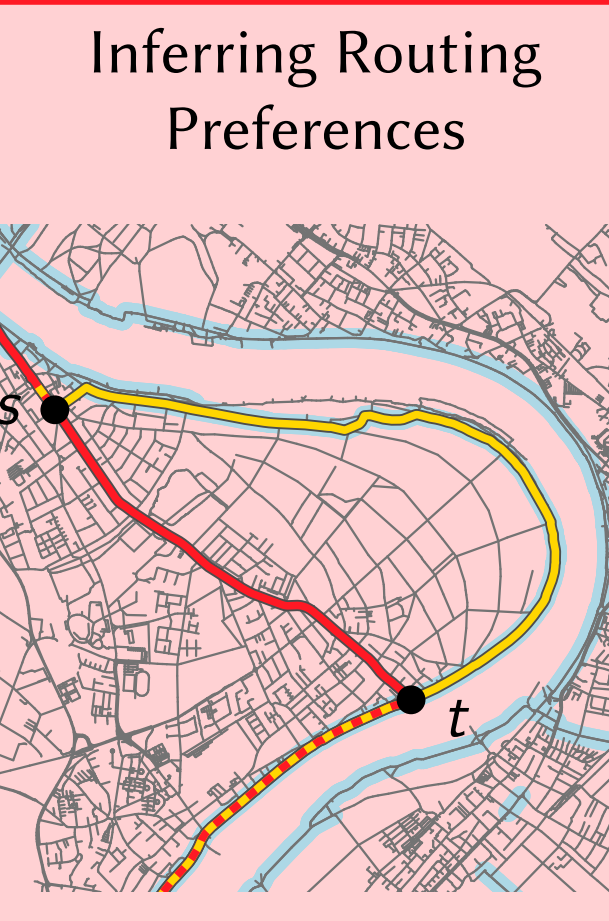
Privacy



A diagram illustrating privacy. It shows two trajectories, T and T' , on a road network. The trajectories are shown as black lines with dots representing user locations. Red squares represent the user's location at different points along the trajectories. The trajectories are labeled T and T' . The user's location at a specific point is labeled $C(\tilde{s})$ and \tilde{s} .

Analysis

Inferring Routing Preferences



A diagram illustrating inferring routing preferences. It shows a map of a city with a river. A red line represents the user's trajectory, and a yellow line represents the inferred routing preference. The trajectory starts at point s and ends at point t . The map is highlighted with a red border.

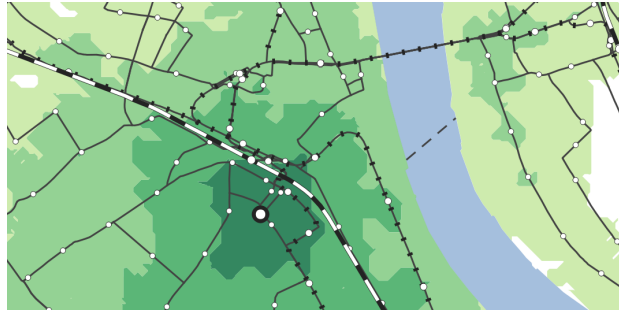
Visualization

Off-screen Evolution



A diagram illustrating off-screen evolution. It shows a map of a city with a river. A red line represents the user's trajectory, and a blue arrow indicates the direction of travel. The trajectory is shown as a red line that curves around the river.

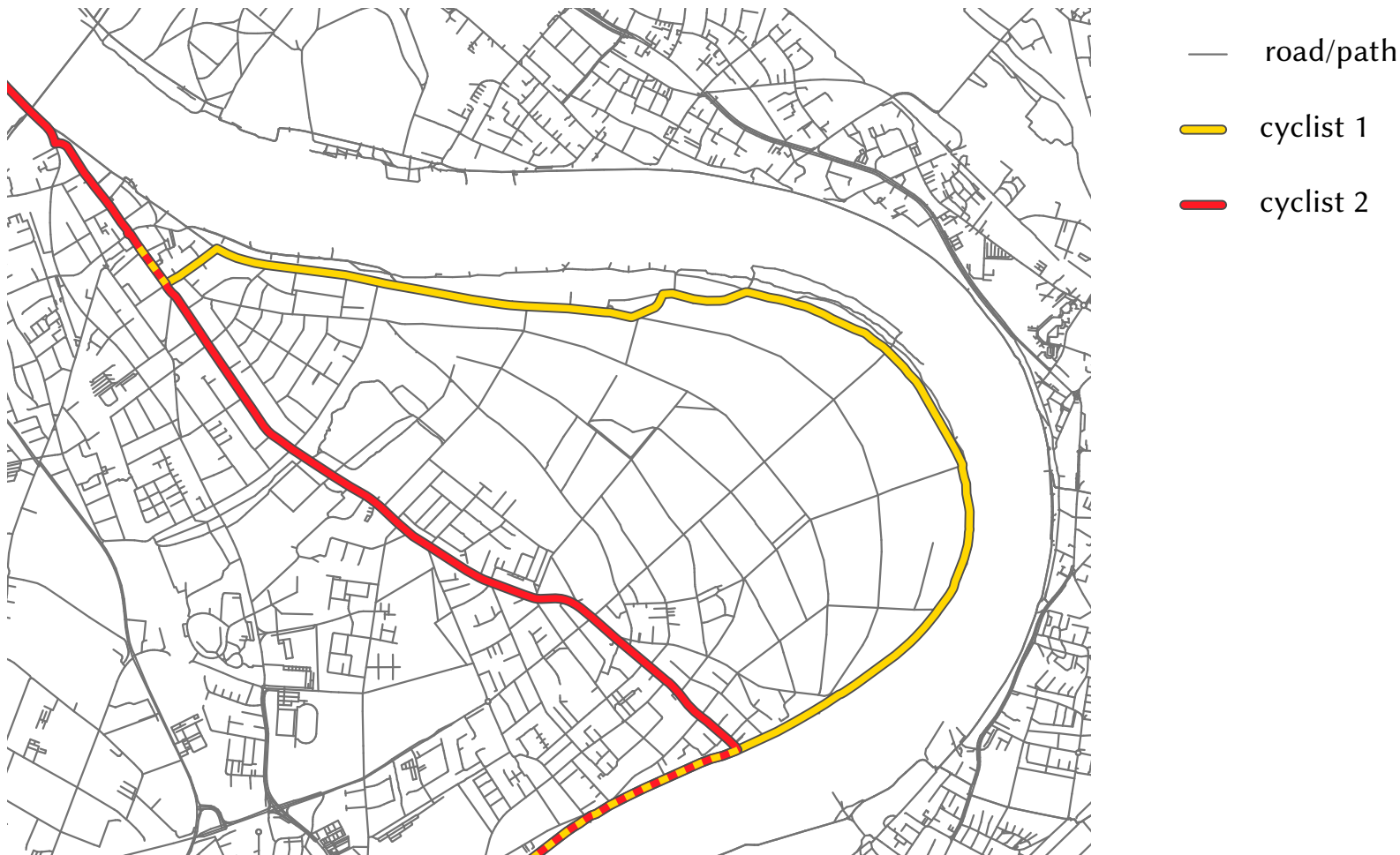
Travel-Time Maps



A diagram illustrating travel-time maps. It shows a map of a city with a river. A network of black lines represents the road network. A red line represents the user's trajectory. The map is highlighted with a red border.

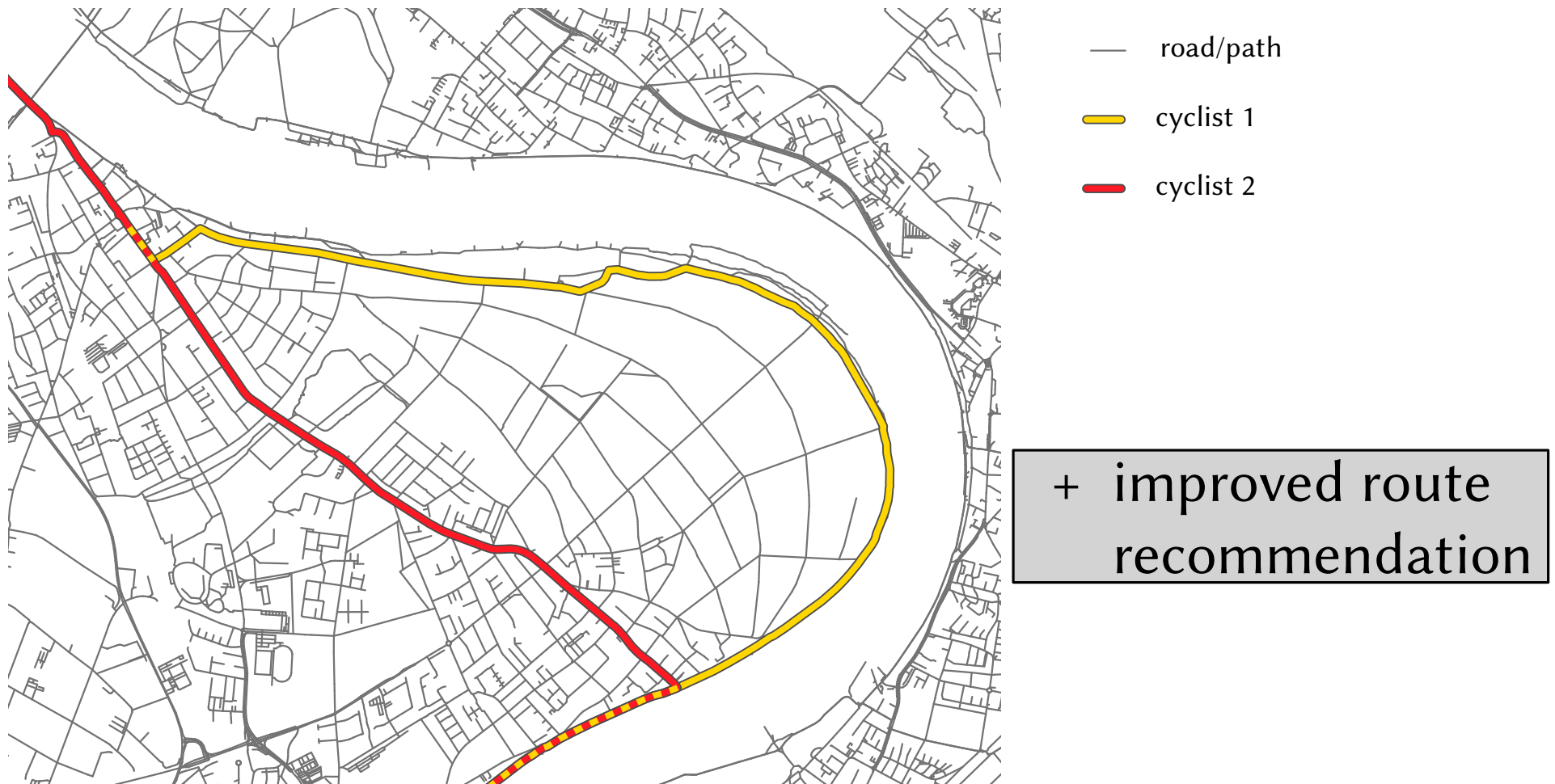
Routing Preferences

- What can we learn from **sparse sets** of trajectories, e.g., a few trajectories recorded by a single user or group of users?



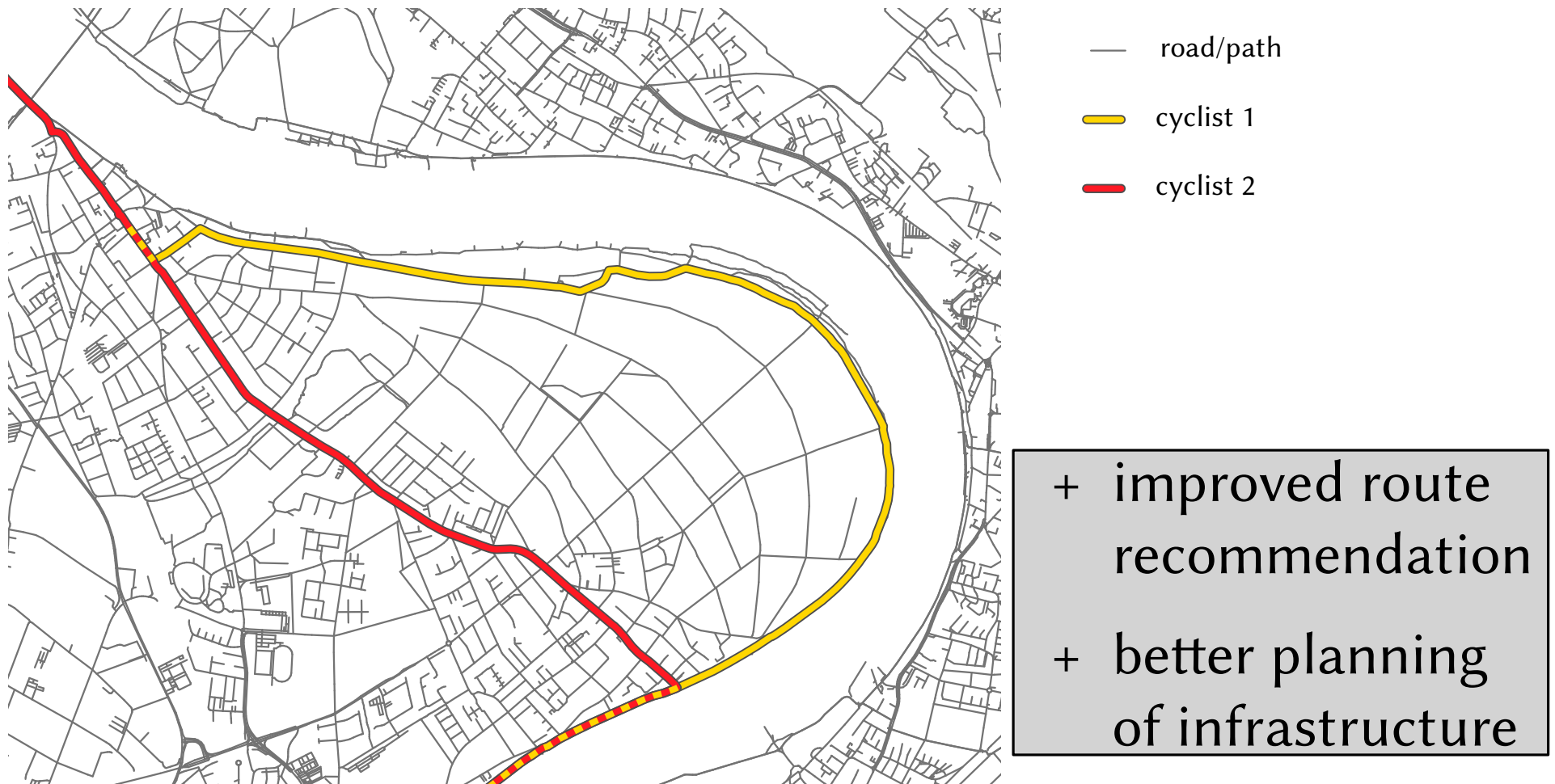
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Routing Preferences

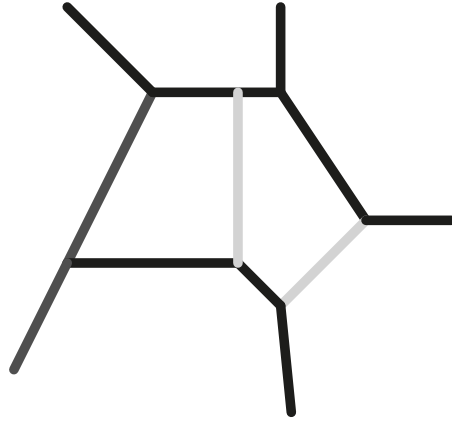
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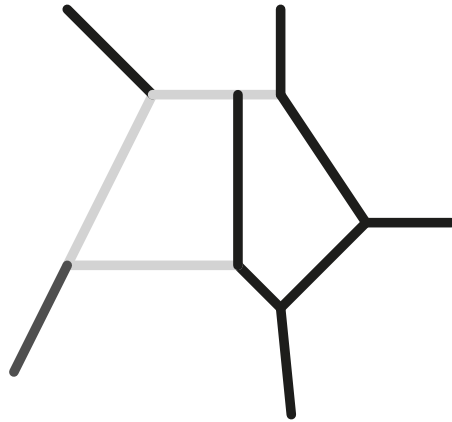
Bicriteria Preference Model

Influence factors

w_1



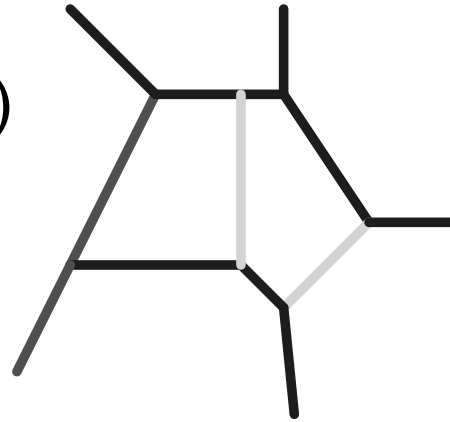
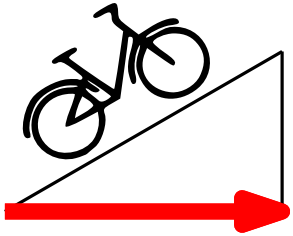
w_2



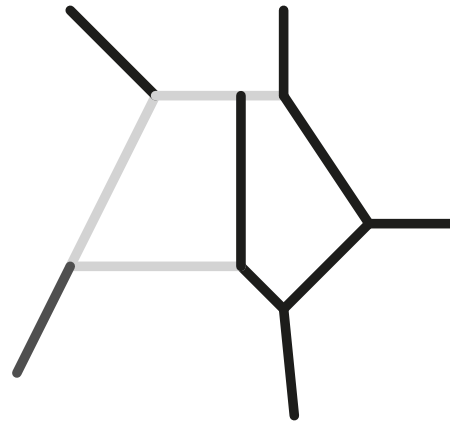
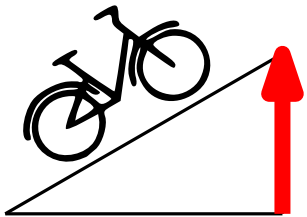
Bicriteria Preference Model

Influence factors

w_1 (2D geom. dist.)



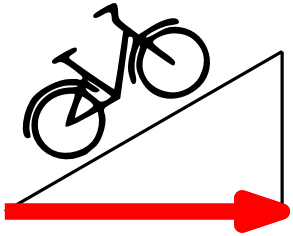
w_2 (climb up)



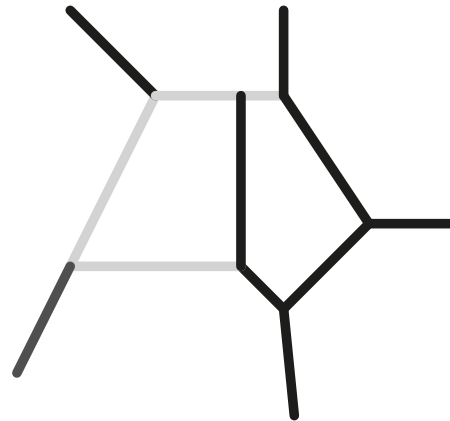
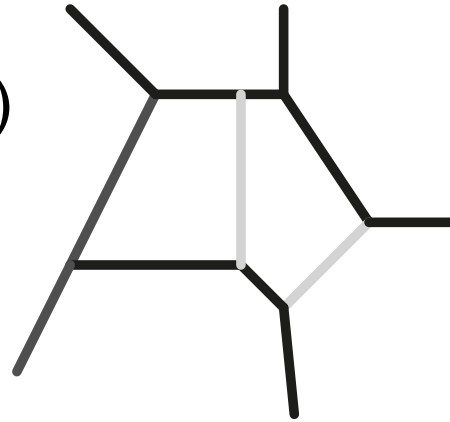
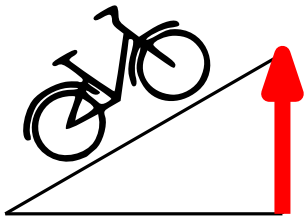
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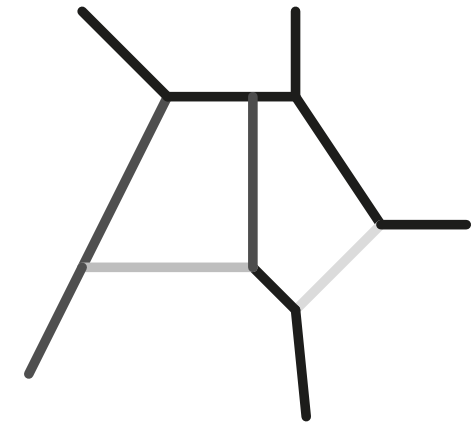
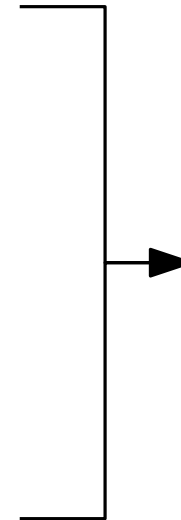


w_2 (climb up)



Personalized weighting

$$w_\alpha = (1 - \alpha) \cdot w_1 + \alpha \cdot w_2$$

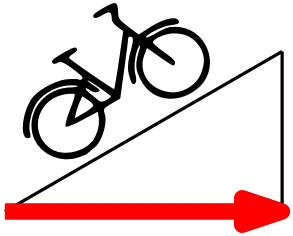


α -optimal path

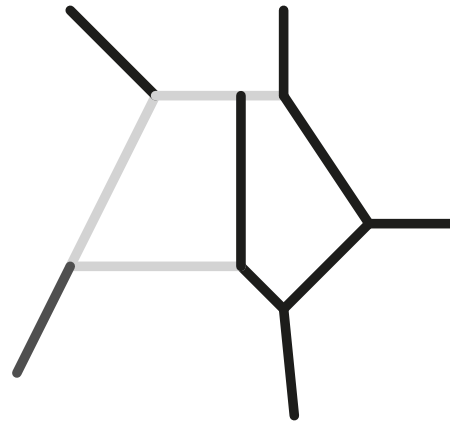
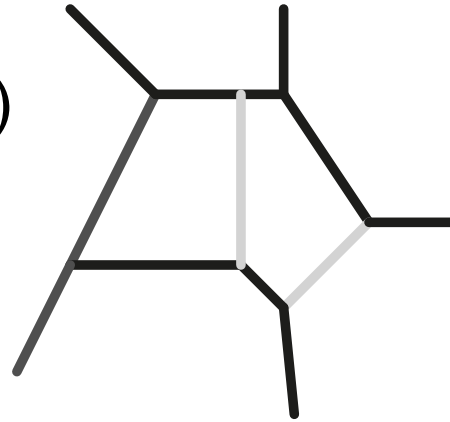
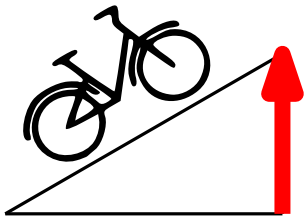
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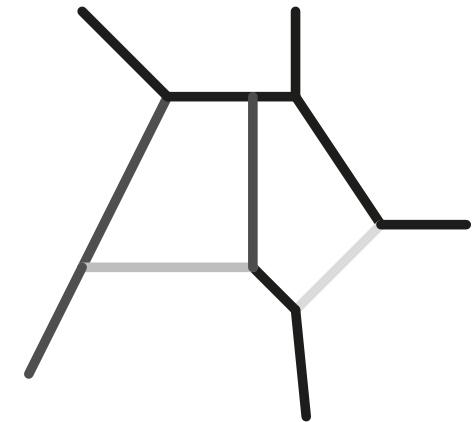
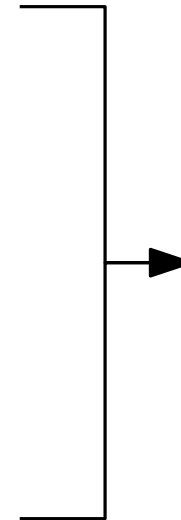


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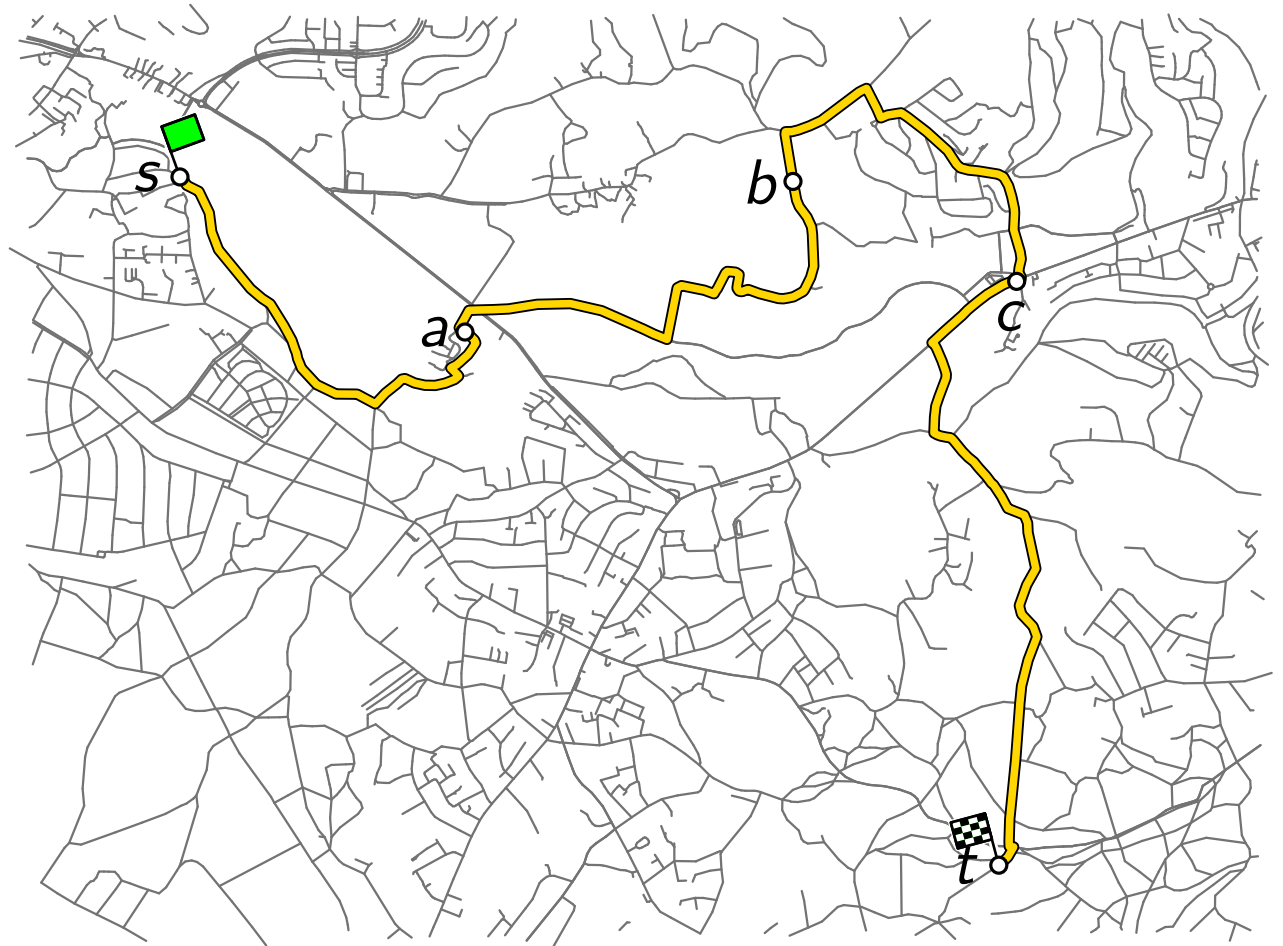


α -optimal path

How can we learn the parametric weight α from a given trajectory?

Milestone Segmentation

segment the trajectory into α -optimal subpaths

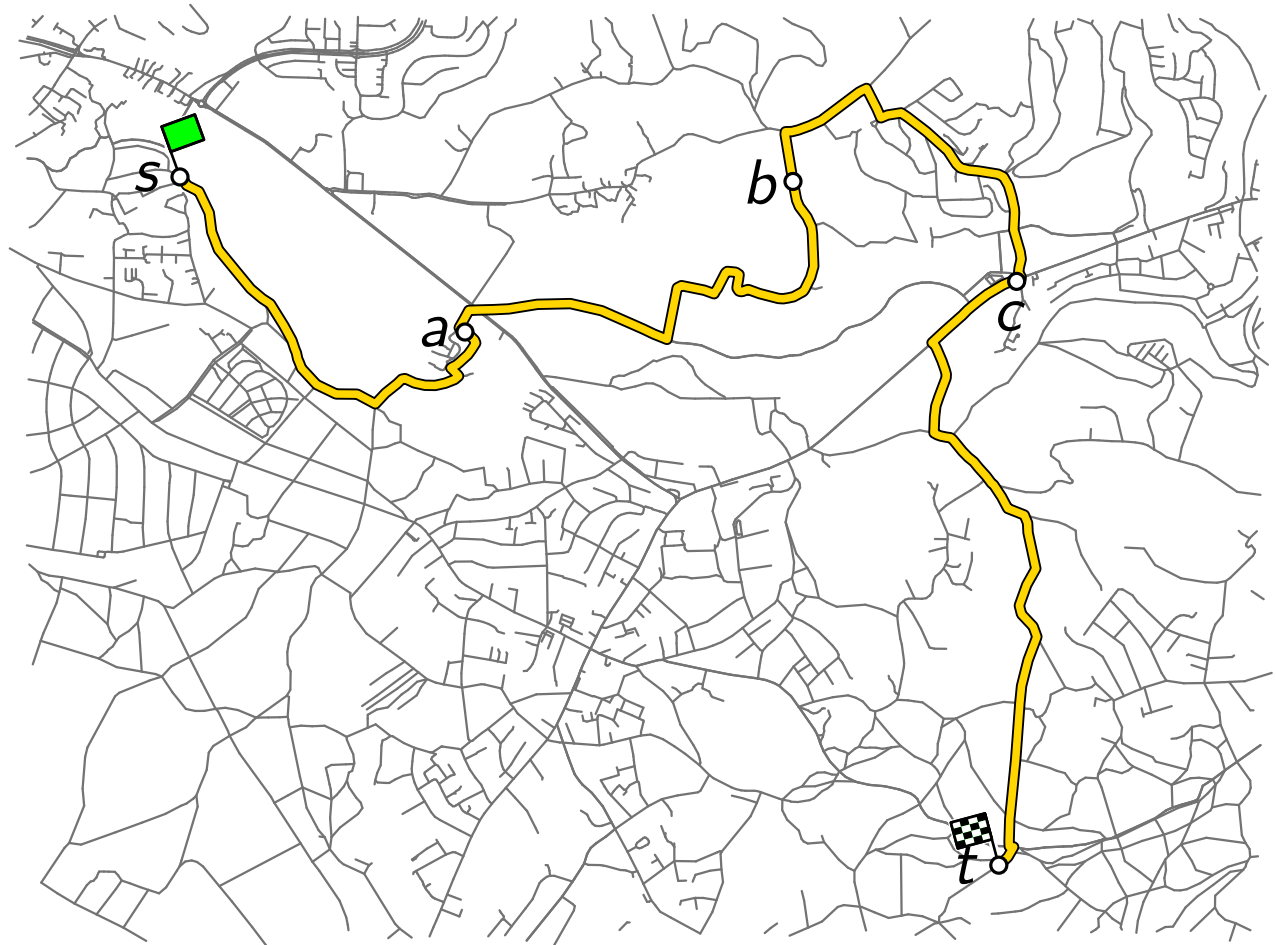


Milestone Segmentation

segment the trajectory into α -optimal subpaths

Compression criterion:

the fewer subpaths are needed, the better α matches the routing preference



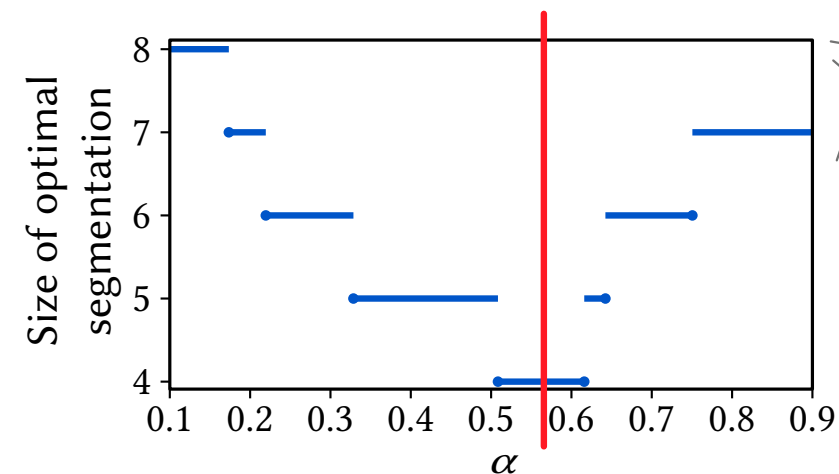
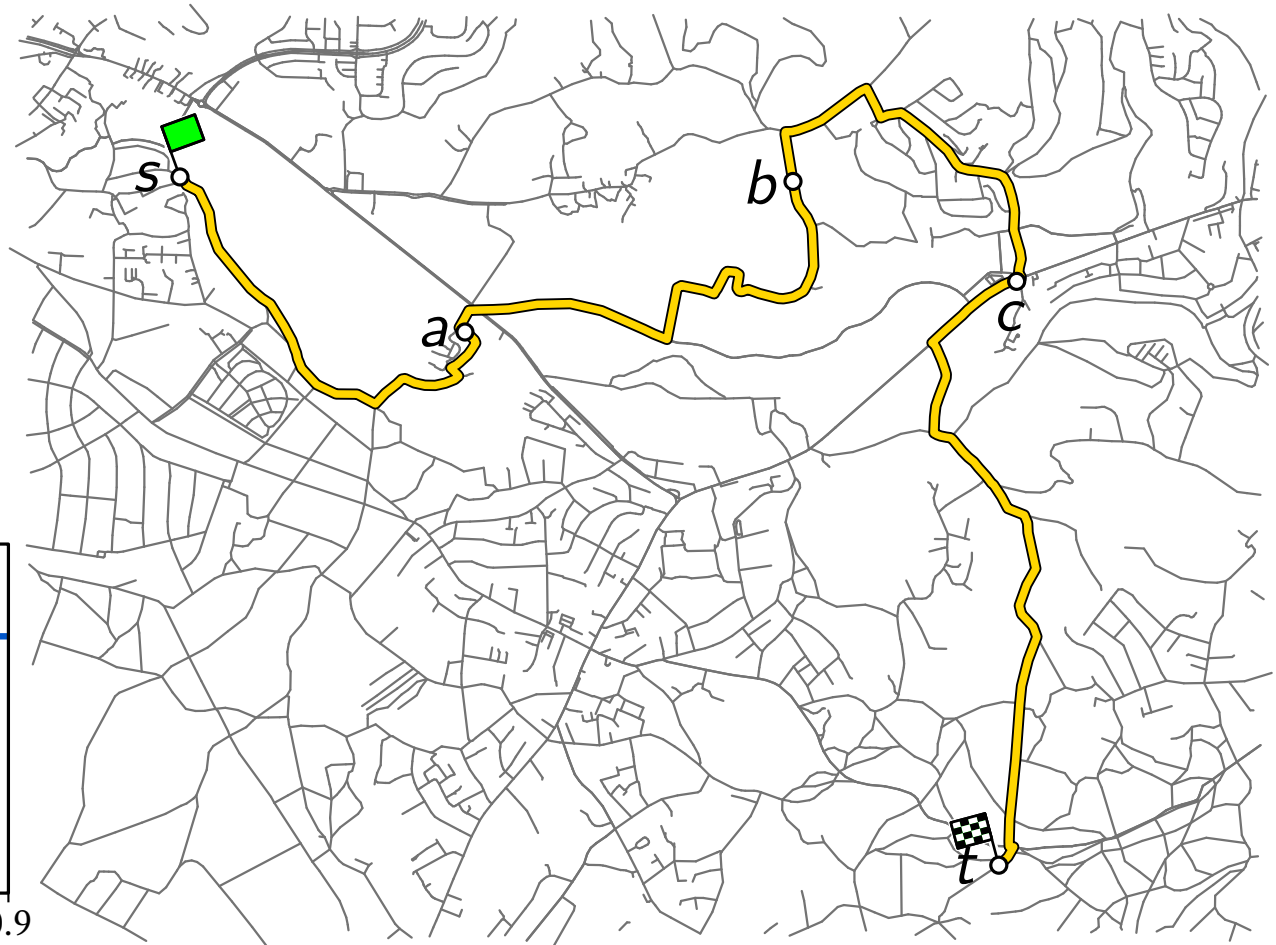
Milestone Segmentation

segment the trajectory into α -optimal subpaths

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$$\alpha = 0.56$$



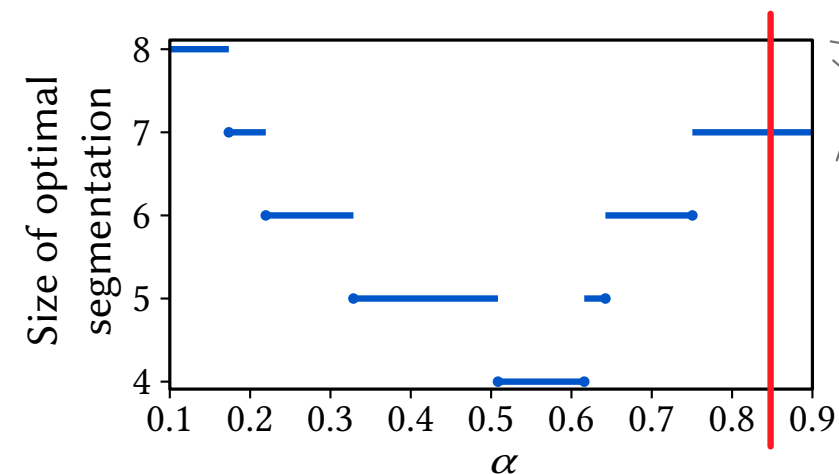
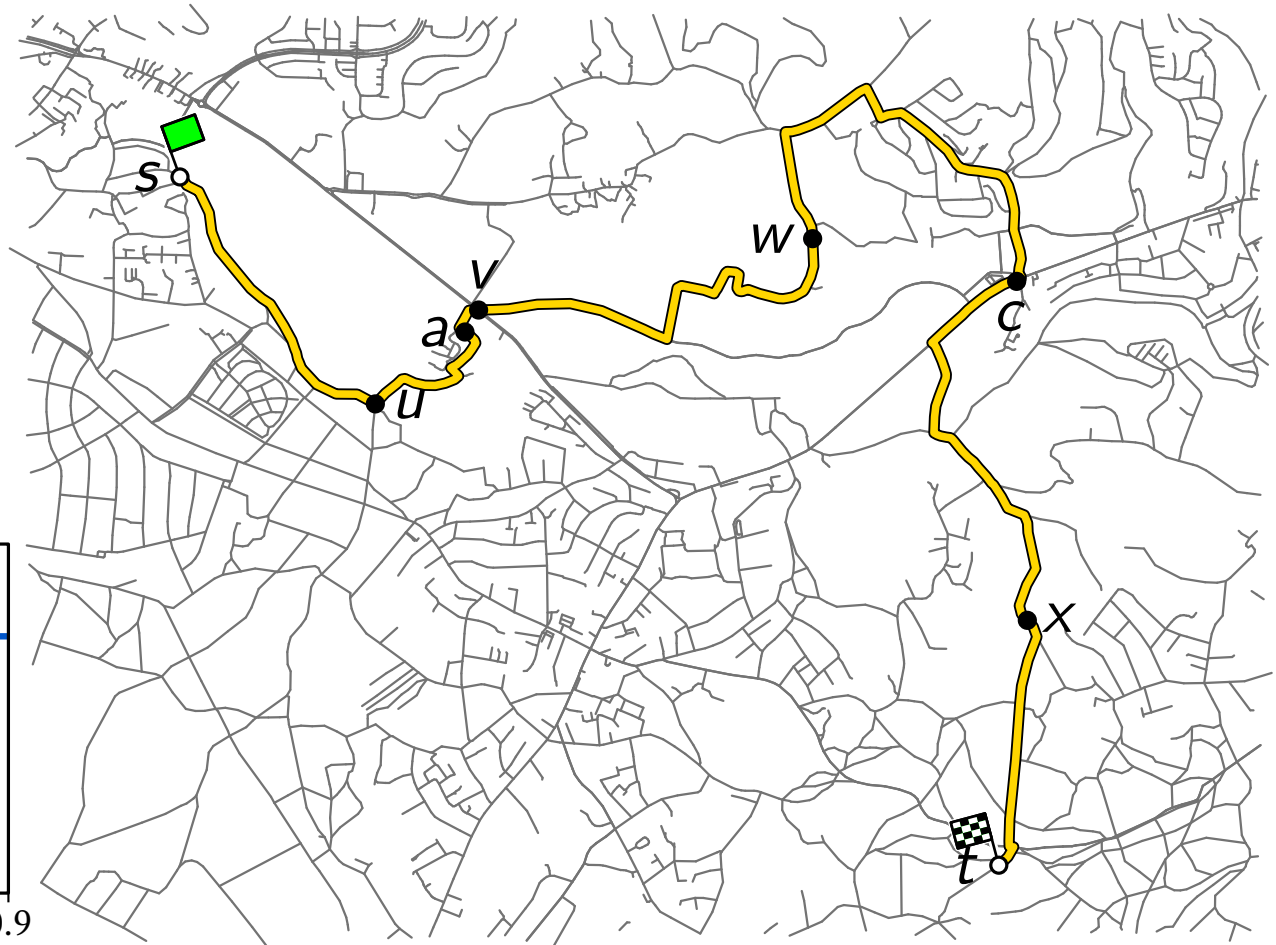
Milestone Segmentation

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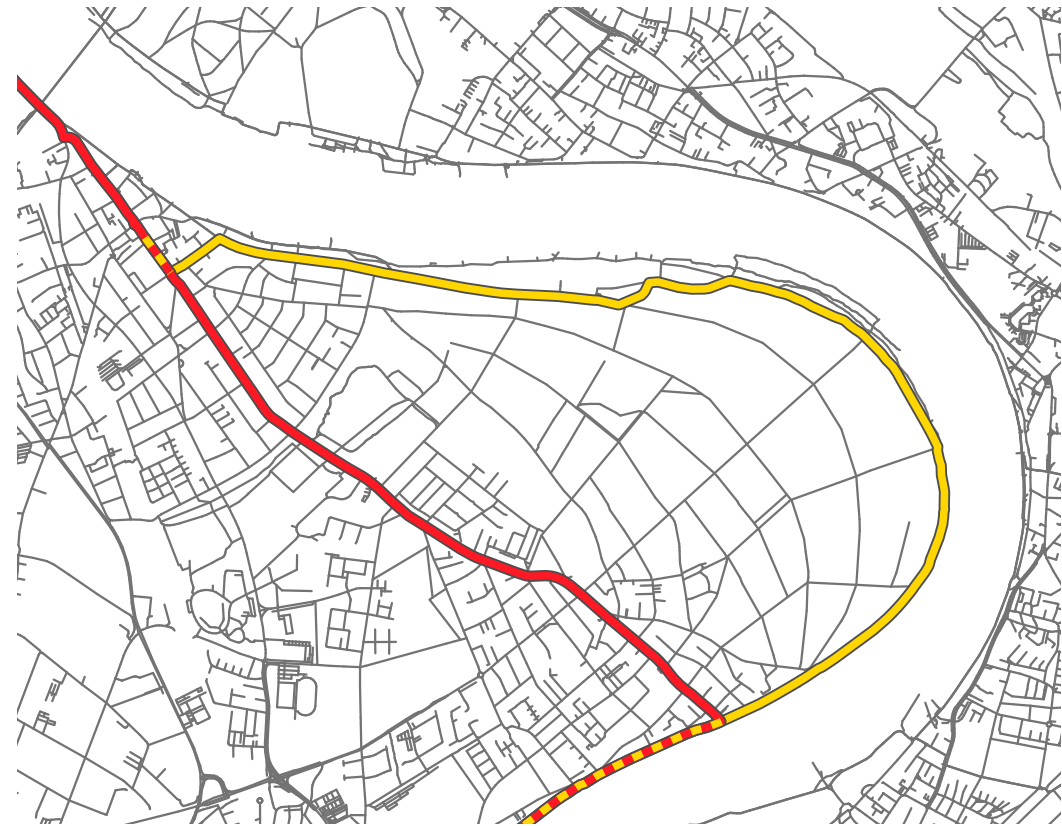
Compression criterion:

the fewer subpaths are needed, the better α matches the routing preference

$\alpha = 0.80$



Signposted Cycling Routes

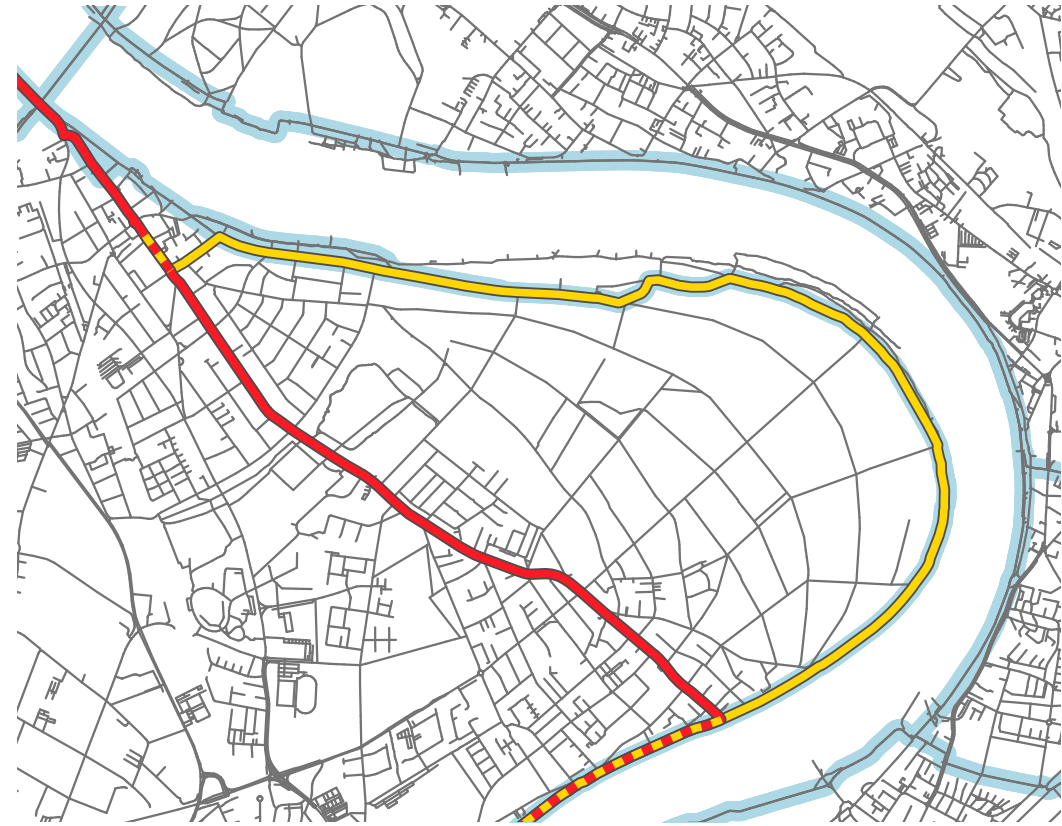


— road/path

— cyclist 1

— cyclist 2

Signposted Cycling Routes



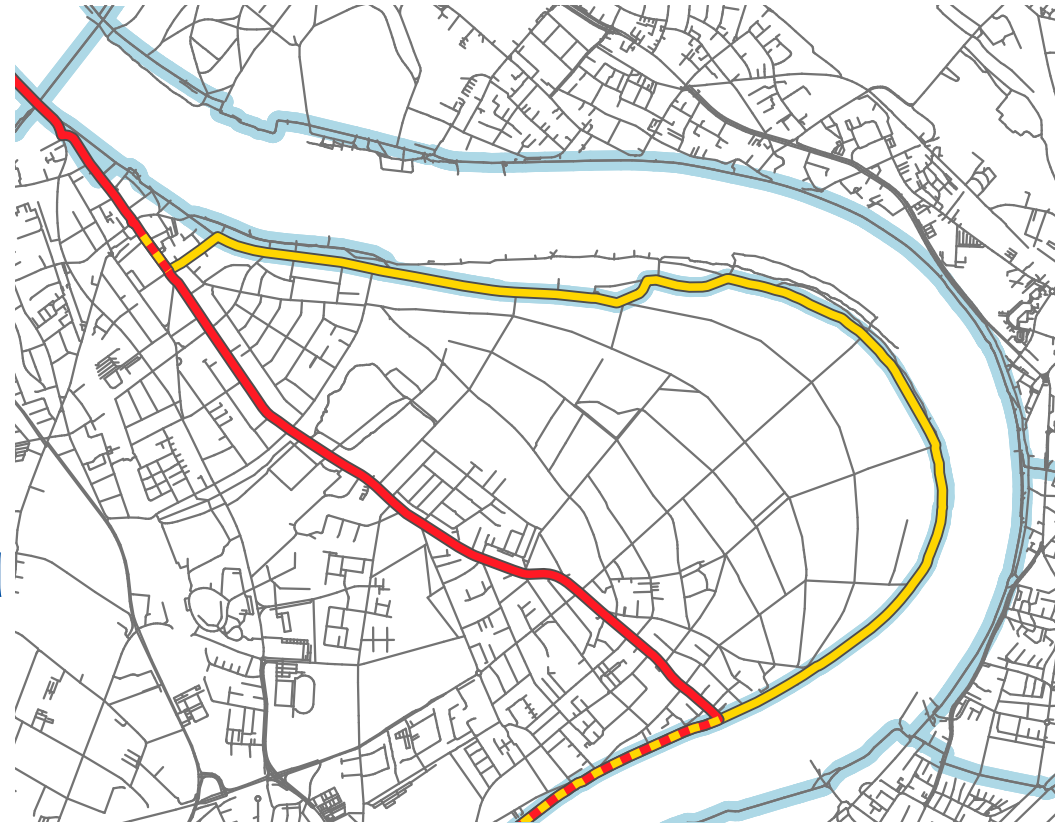
- road/path
- cyclist 1
- cyclist 2
- signposted cycleway

Signposted Cycling Routes

$$w_{\alpha}(P) = (1 - \alpha) \cdot w_r(P) + \alpha \cdot w_c(P)$$

$w_r(P)$ = length of all **signposted** sections of path P

$w_c(P)$ = length of all **non-signposted** sections of path P



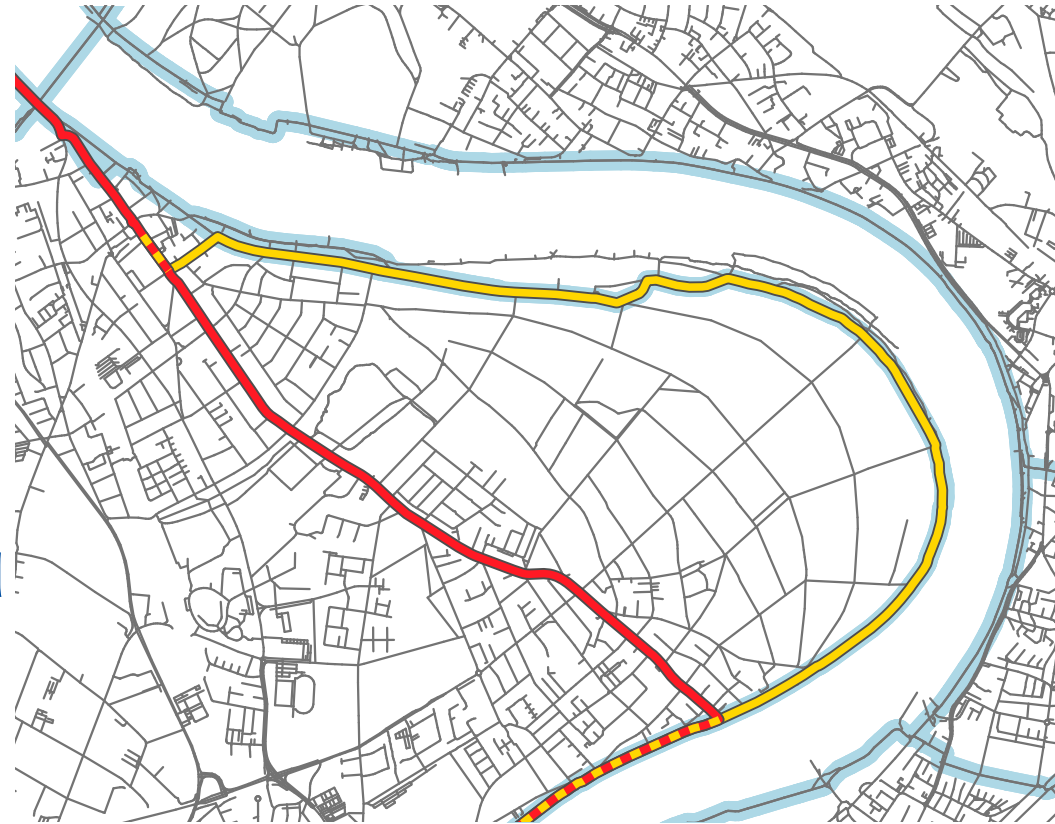
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using this definition makes α interpretable:

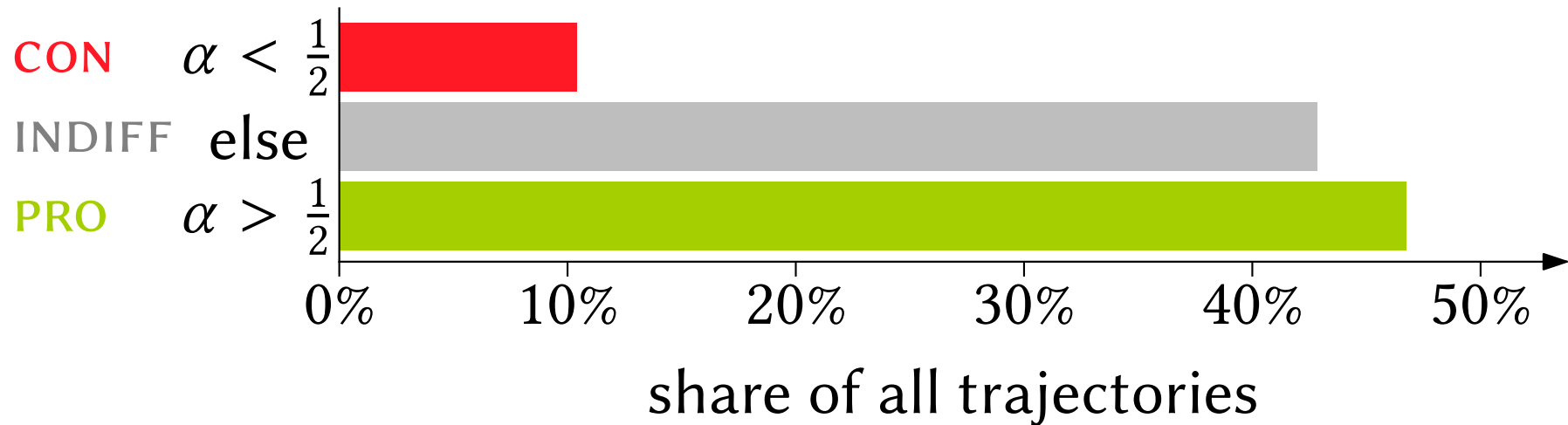
$\alpha = 0.5$ \Rightarrow geometric shortest path

$\alpha = 0.6$ \Rightarrow detour of 50% to stick to signposted ways

- road/path
- cyclist 1
- cyclist 2
- signposted cycleway

Experiments

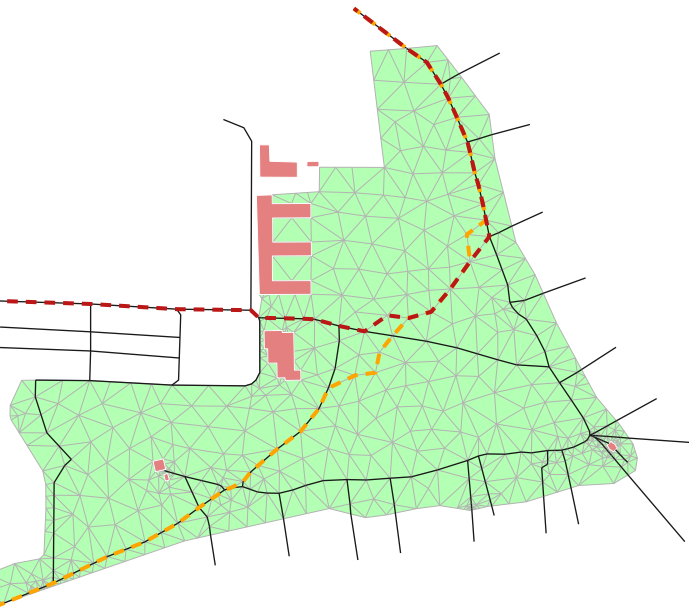
set of 1 758 trajectories recorded by cyclists in Cologne
grouped according to their preference on signposted paths



cyclists in the group **PRO** are willing to cover more than 40%
extra distance in order to stick to signposted paths

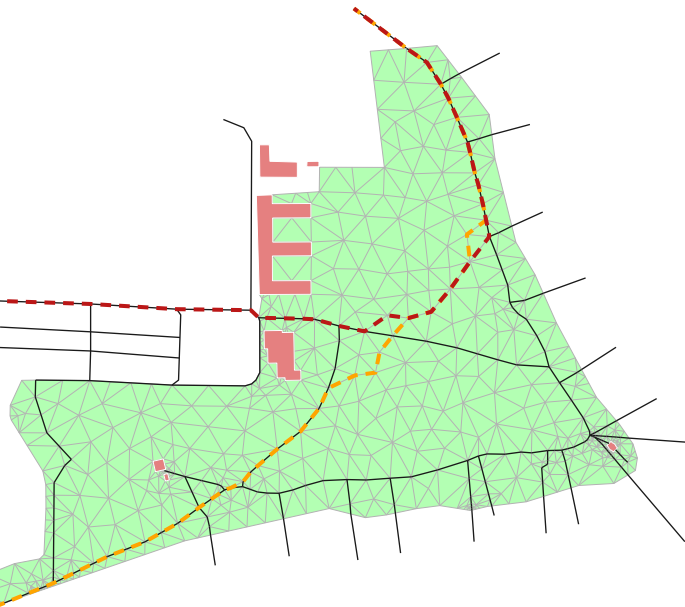
Trajectory Processing Toolchain

Map Matching

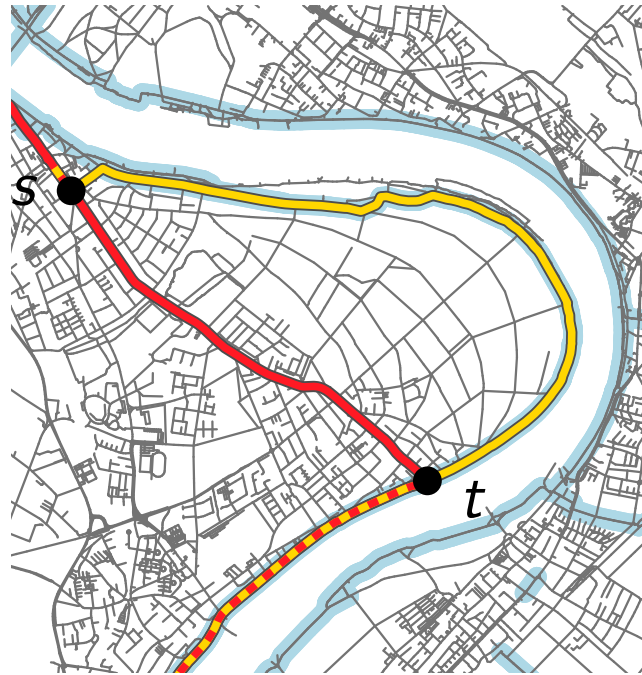


Trajectory Processing Toolchain

Map Matching

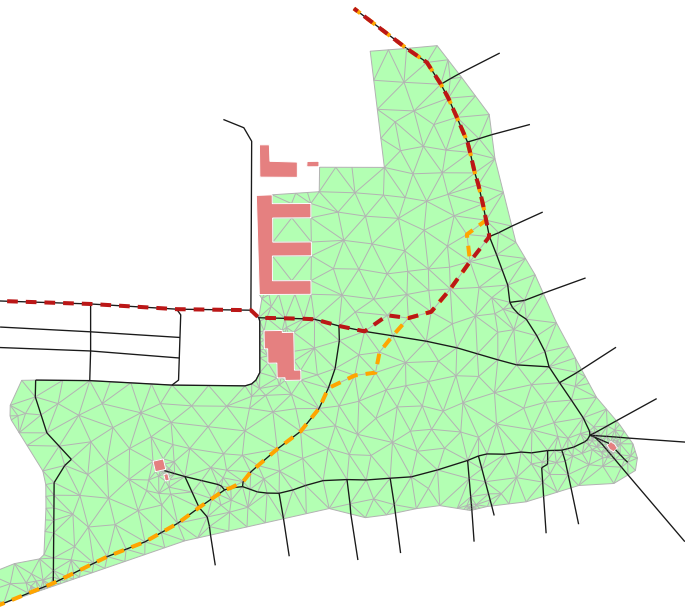


Learning Routing
Preferences

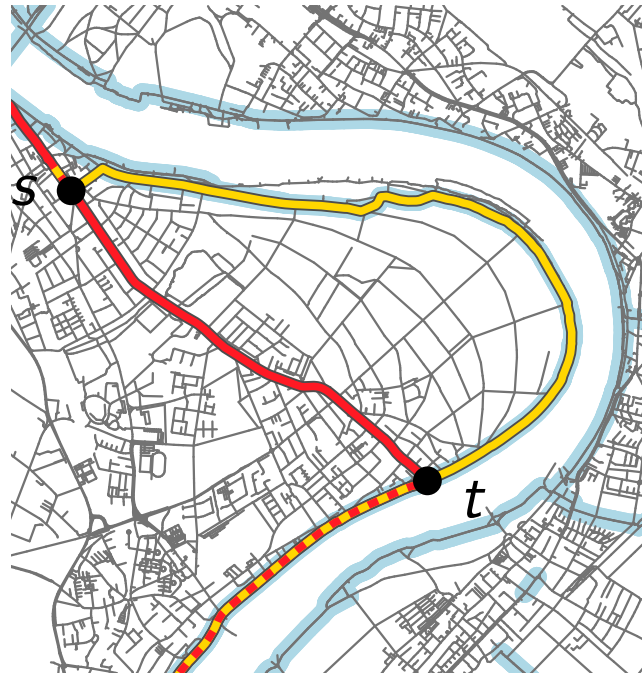


Trajectory Processing Toolchain

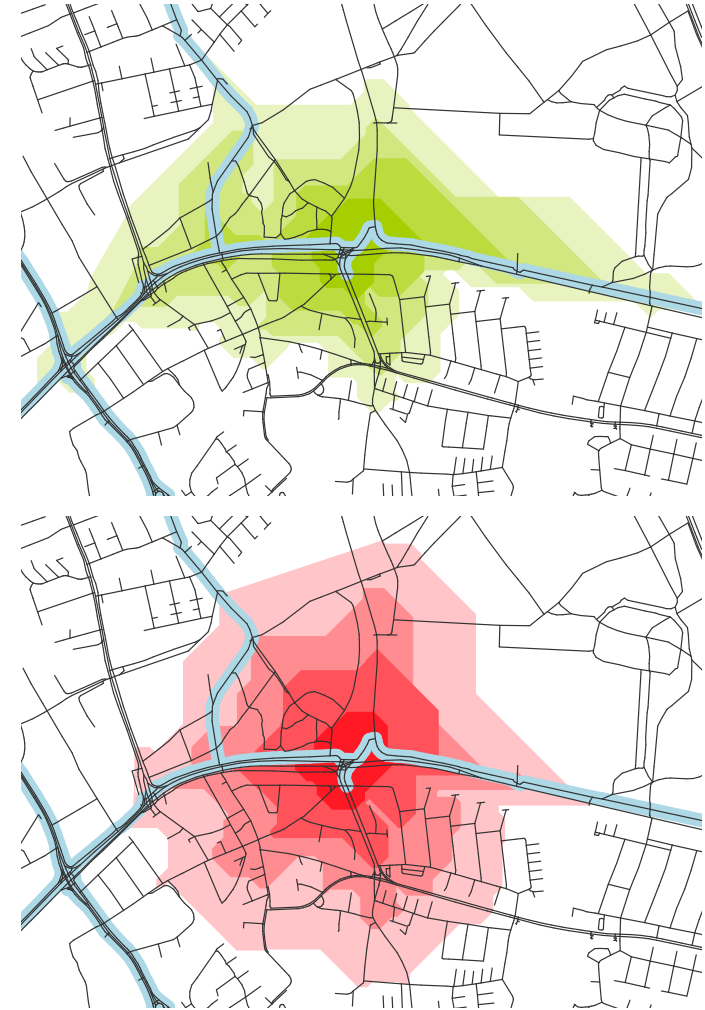
Map Matching



Learning Routing Preferences

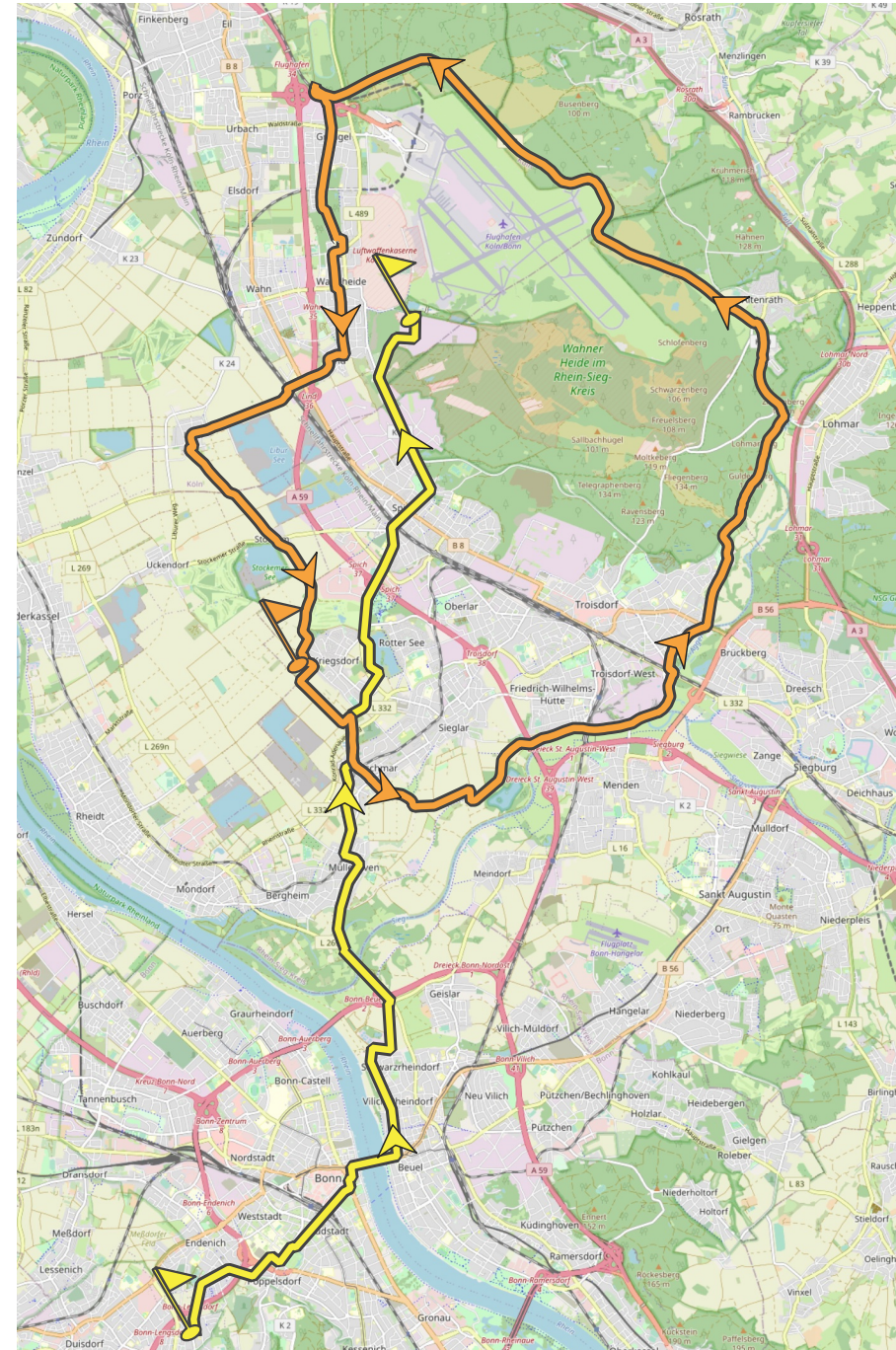


Visualization



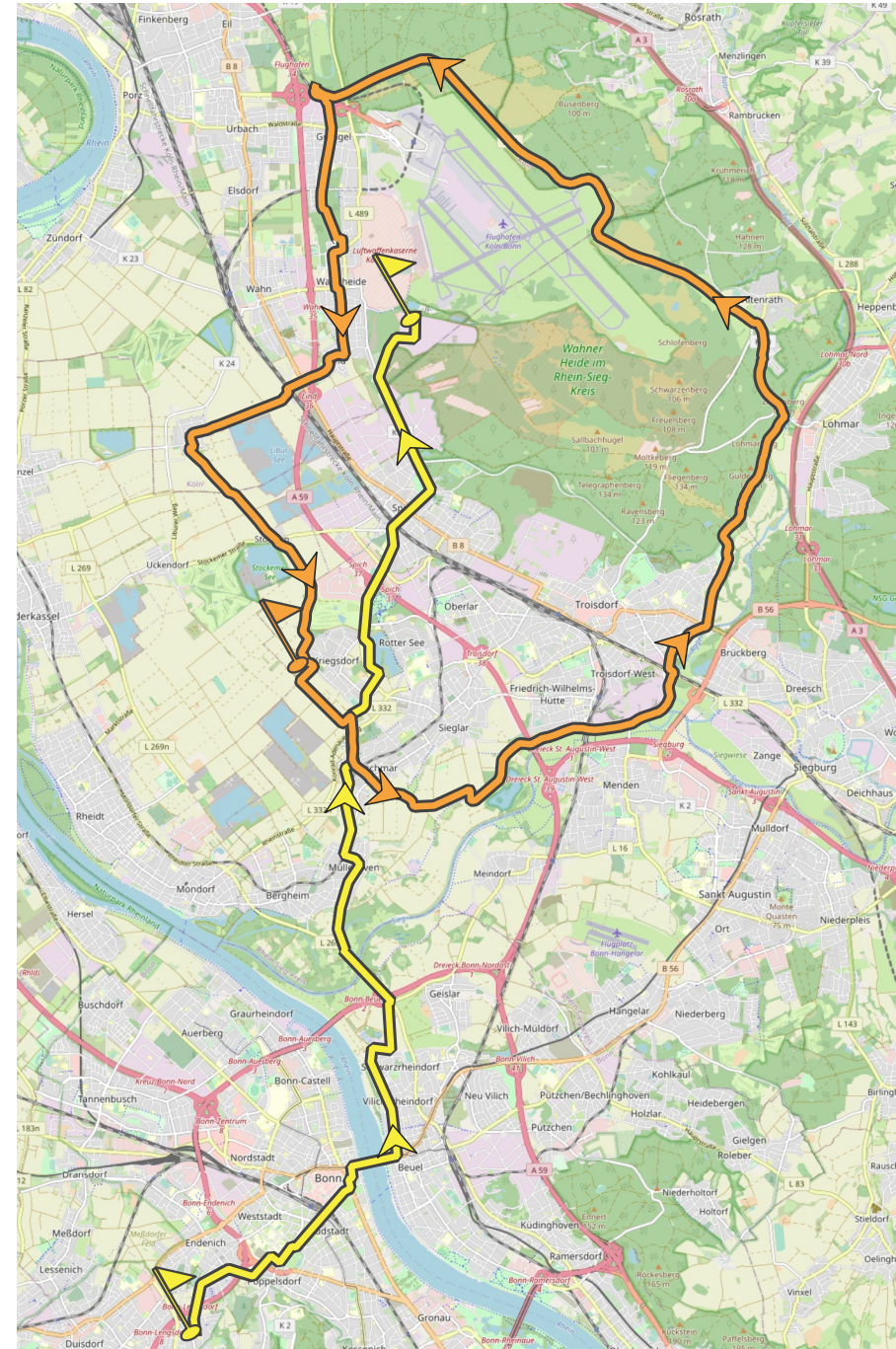
Main Contribution

Tool to infer routing preferences from trajectories



Main Contribution

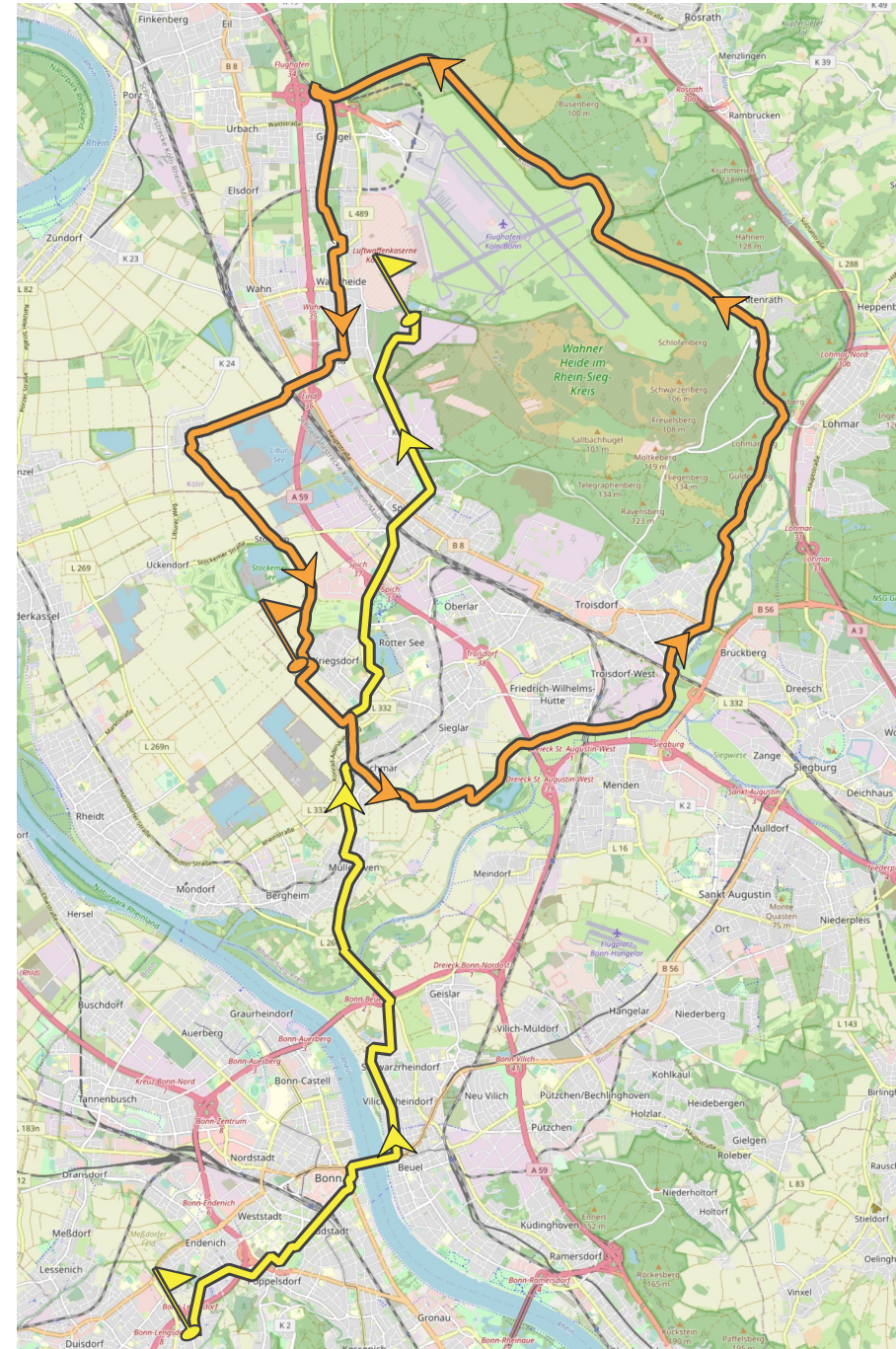
Tool to infer routing preferences from trajectories
- applicable for **all** trajectories



Main Contribution

Tool to infer routing preferences from trajectories

- applicable for **all** trajectories
- applicable for **single** trajectories



Main Contribution

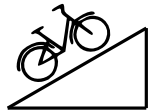
Tool to infer routing preferences from trajectories

- applicable for **all** trajectories
- applicable for **single** trajectories
- detected significant influence of:

- signposted cycleways



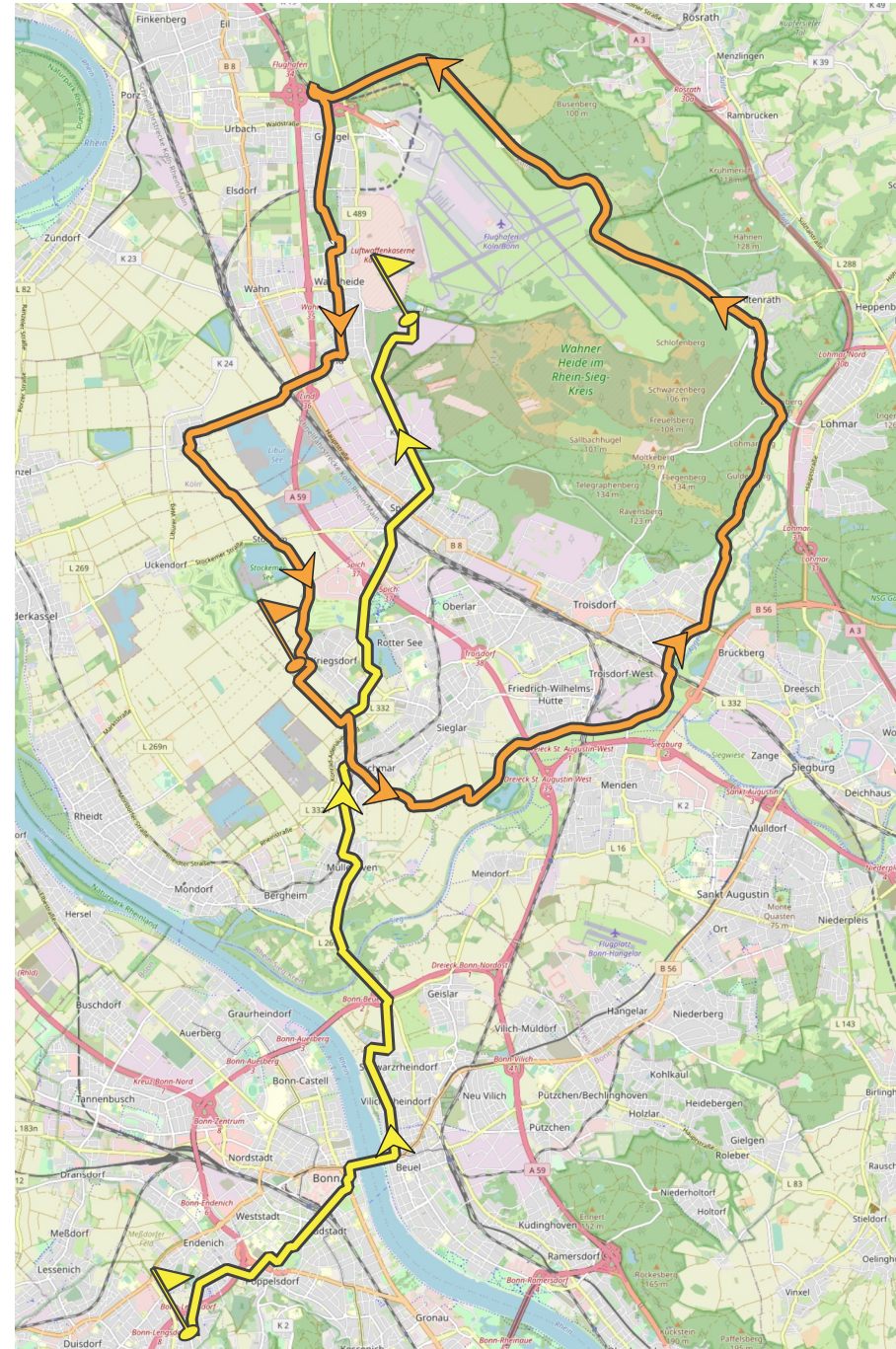
- route ascent



- route complexity

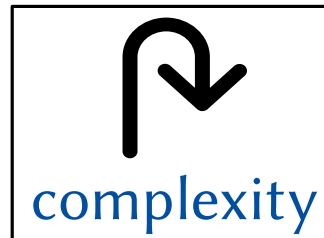


on routing behavior



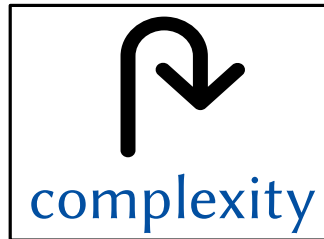
Future Work

- extend approach for multiple criteria



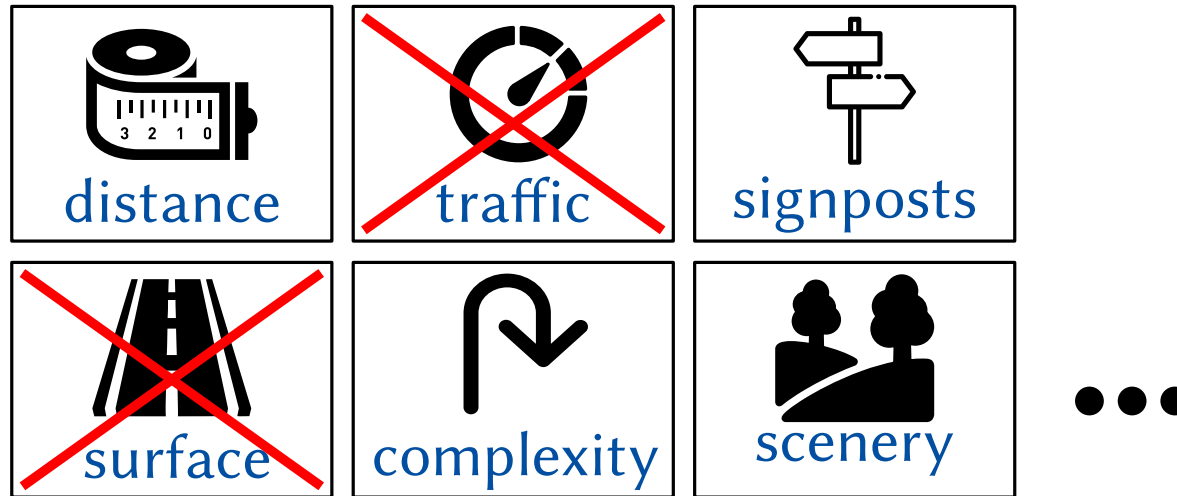
Future Work

- extend approach for multiple criteria



Future Work

- extend approach for multiple criteria



- validate results based on explicit preferences
 - explicit → as stated by user
 - implicit → as shown by behavior

Thank you for your attention!

Forsch, A., Dehbi, Y., Niedermann, B., Oehrlein, J., Rottmann, P., & Haunert, J. H. (2021). Multimodal travel-time maps with formally correct and schematic isochrones. *Transactions in GIS*, 25, 3233–3256.

Behr, T., van Dijk, T. C., **Forsch, A.**, Haunert, J. H., & Storandt, S. (2021). Map Matching for Semi-Restricted Trajectories. In *11th International Conference on Geographic Information Science (GIScience 2021)-Part II*. Schloss Dagstuhl-Leibniz-Zentrum für Informatik.

Brauer, A., Mäkinen, V., **Forsch, A.**, Oksanen, J., Haunert, J. H. (2022). My home is my secret: concealing sensitive locations by context-aware trajectory truncation. *International Journal of Geographical Information Science*, **under review**.

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